



Relion® 615 series

Transformer Protection and Control RET615 Product Guide

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Transformer Protection and Control	1MRS756891 L
RET615	
Product version: 5.0 FP1	Issued: 2016-05-20
	Revision: L

1. Description

RET615 is a dedicated transformer protection and control relay for power transformers, unit and step-up transformers including power generator-transformer blocks in utility and industry power distribution systems. RET615 is a member of ABB's Relion® product family and part of its 615 protection and control product series. The 615 series relays are characterized by their compactness and withdrawable-unit design.

Re-engineered from the ground up, the 615 series has been designed to unleash the full potential of the IEC 61850 standard for communication and interoperability between substation automation devices. Once the standard configuration relay has been given the application-specific settings, it can directly be put into service.

The 615 series relays support a range of communication protocols including IEC 61850 with Edition 2 support, process bus according to IEC 61850-9-2 LE, IEC 60870-5-103, Modbus® and DNP3. Profibus DPV1 communication protocol is supported by using the protocol converter SPA-ZC 302.

2. Standard configurations

RET615 is available in eight alternative standard configurations. The standard signal configuration can be altered by means of the signal matrix or the graphical application functionality of the Protection and Control IED Manager PCM600. Further, the application configuration functionality of PCM600 supports the creation of multi-layer logic functions utilizing various logical elements including timers and flip-flops. By combining protection functions with logic function blocks the relay configuration can be adapted to user specific application requirements.

The relay is delivered from the factory with default connections described in the functional diagrams for binary inputs, binary outputs, function-to-function connections and alarm LEDs. Some of the supported functions in RET615 must be added with the Application Configuration tool to be available in the Signal Matrix tool and in the relay. The positive measuring direction of directional protection functions is towards the outgoing feeder.

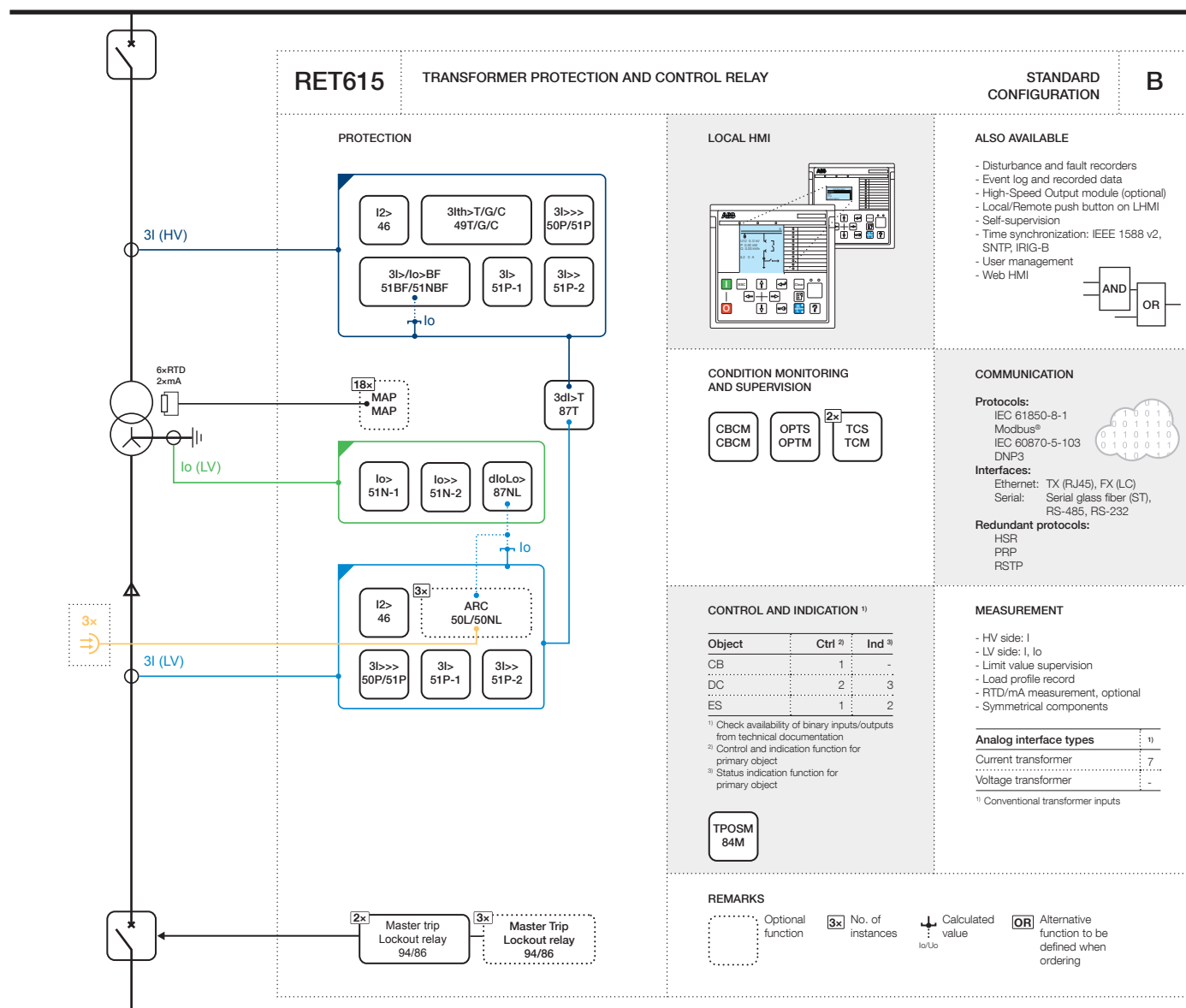
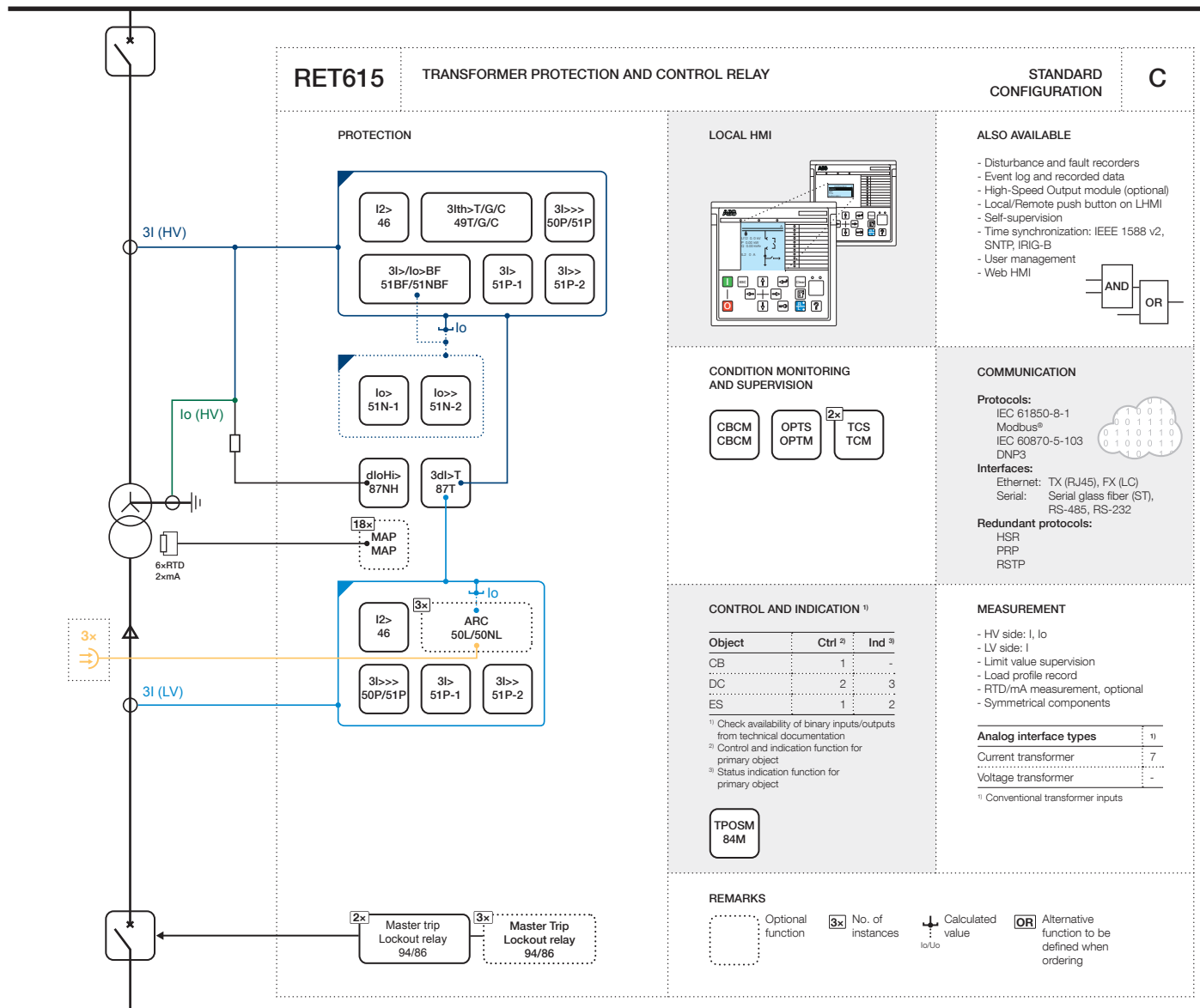


Figure 2. Functionality overview for standard configuration B



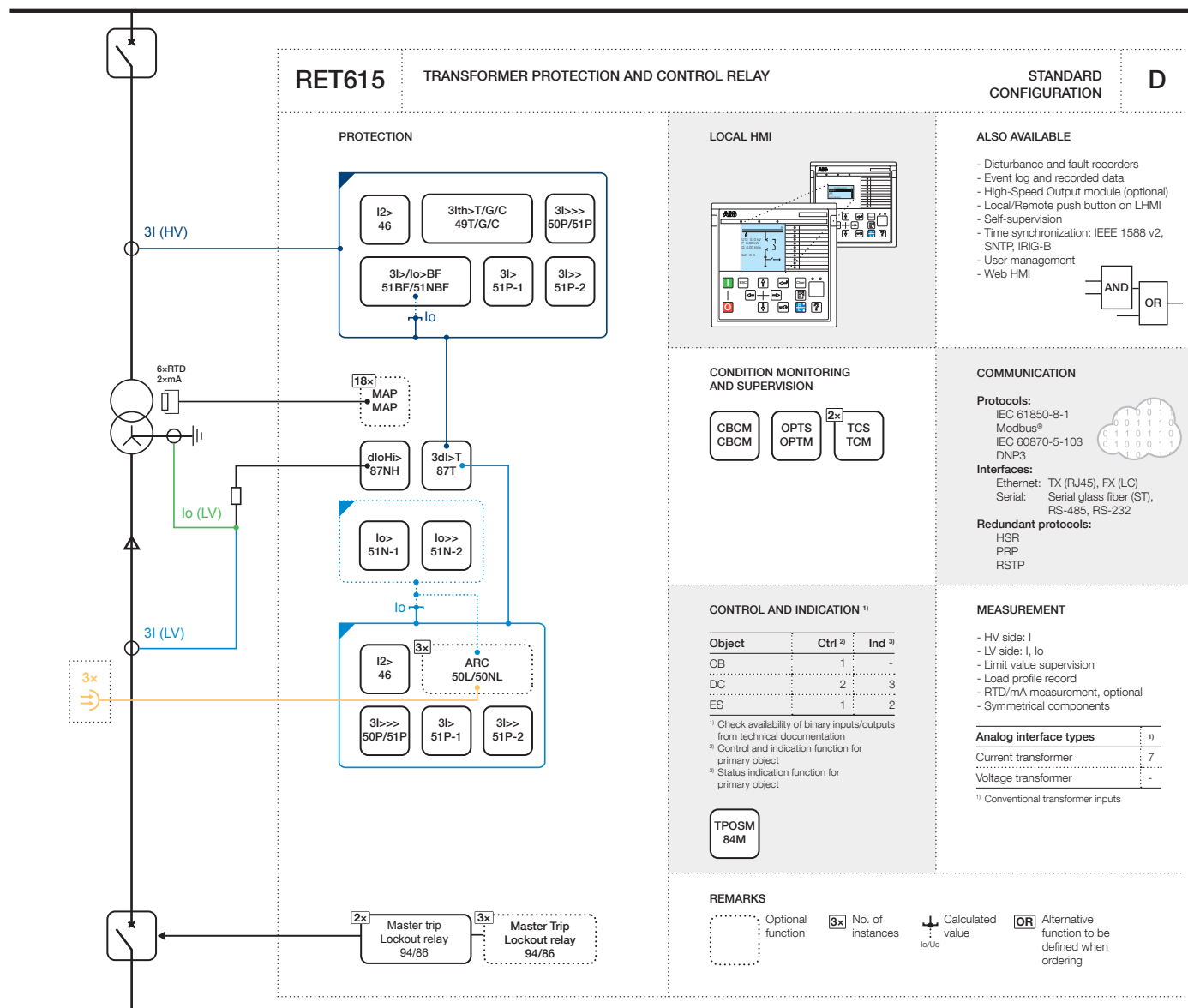


Figure 4. Functionality overview for standard configuration D

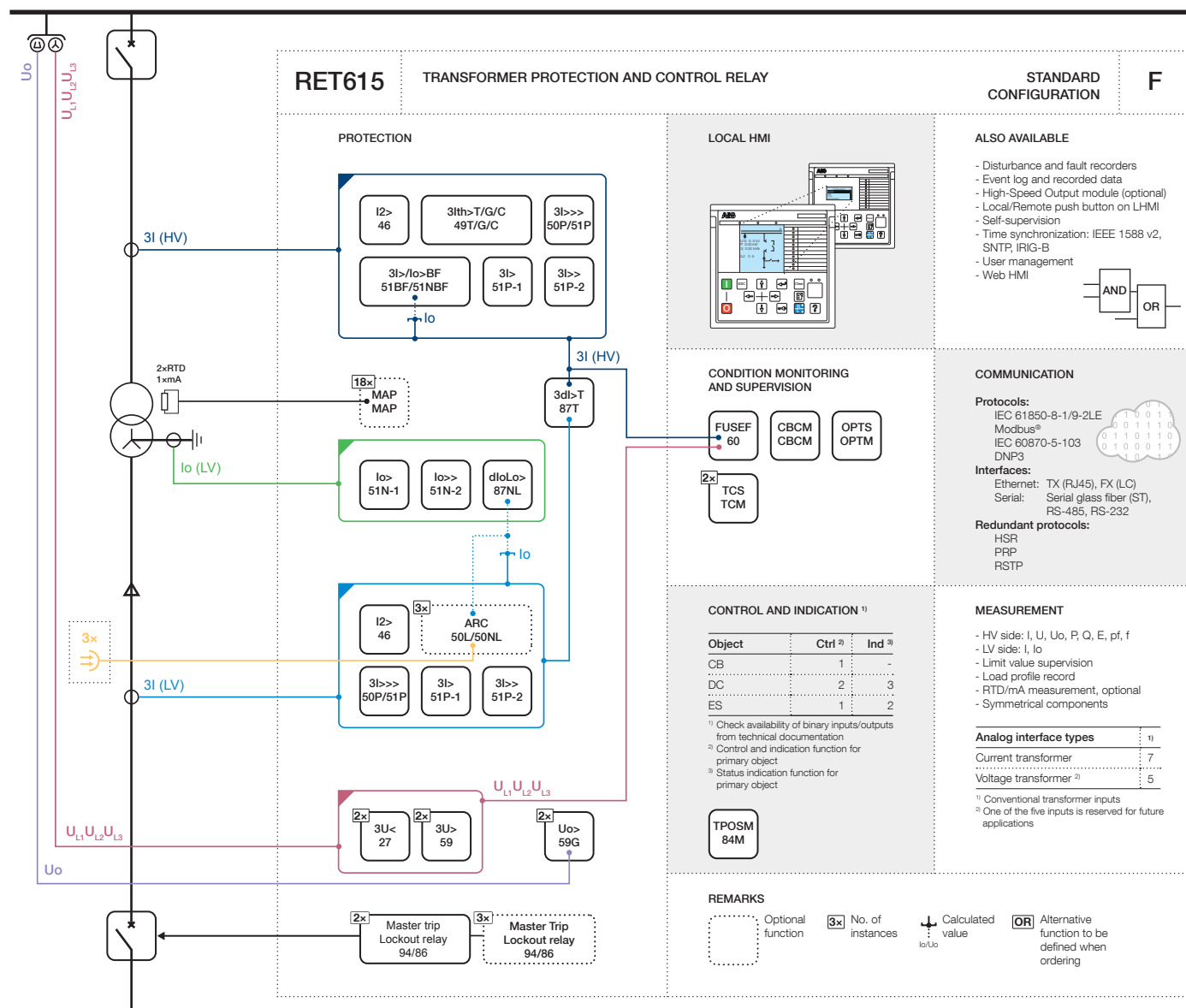


Figure 6. Functionality overview for standard configuration F

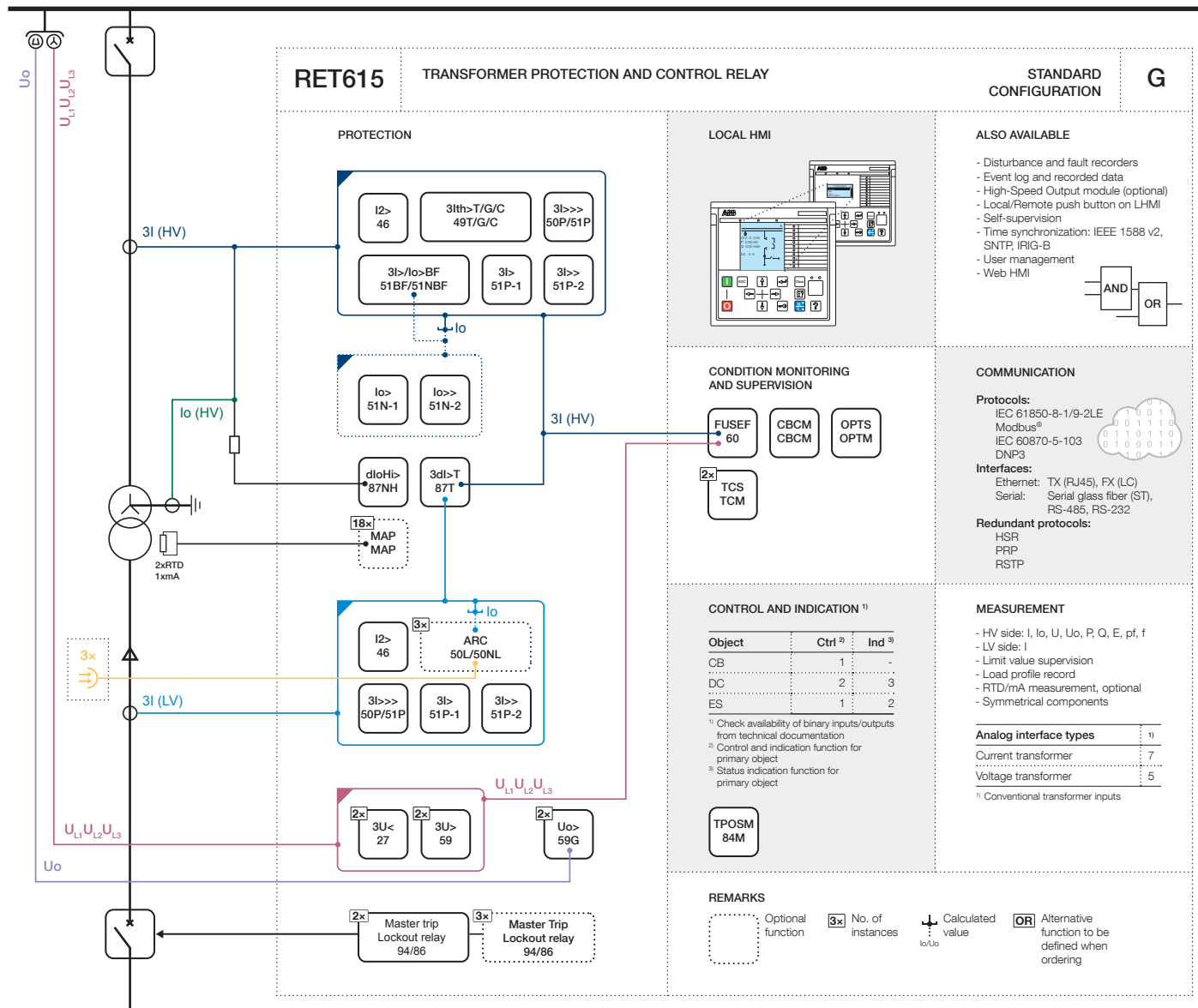


Figure 7. Functionality overview for standard configuration G

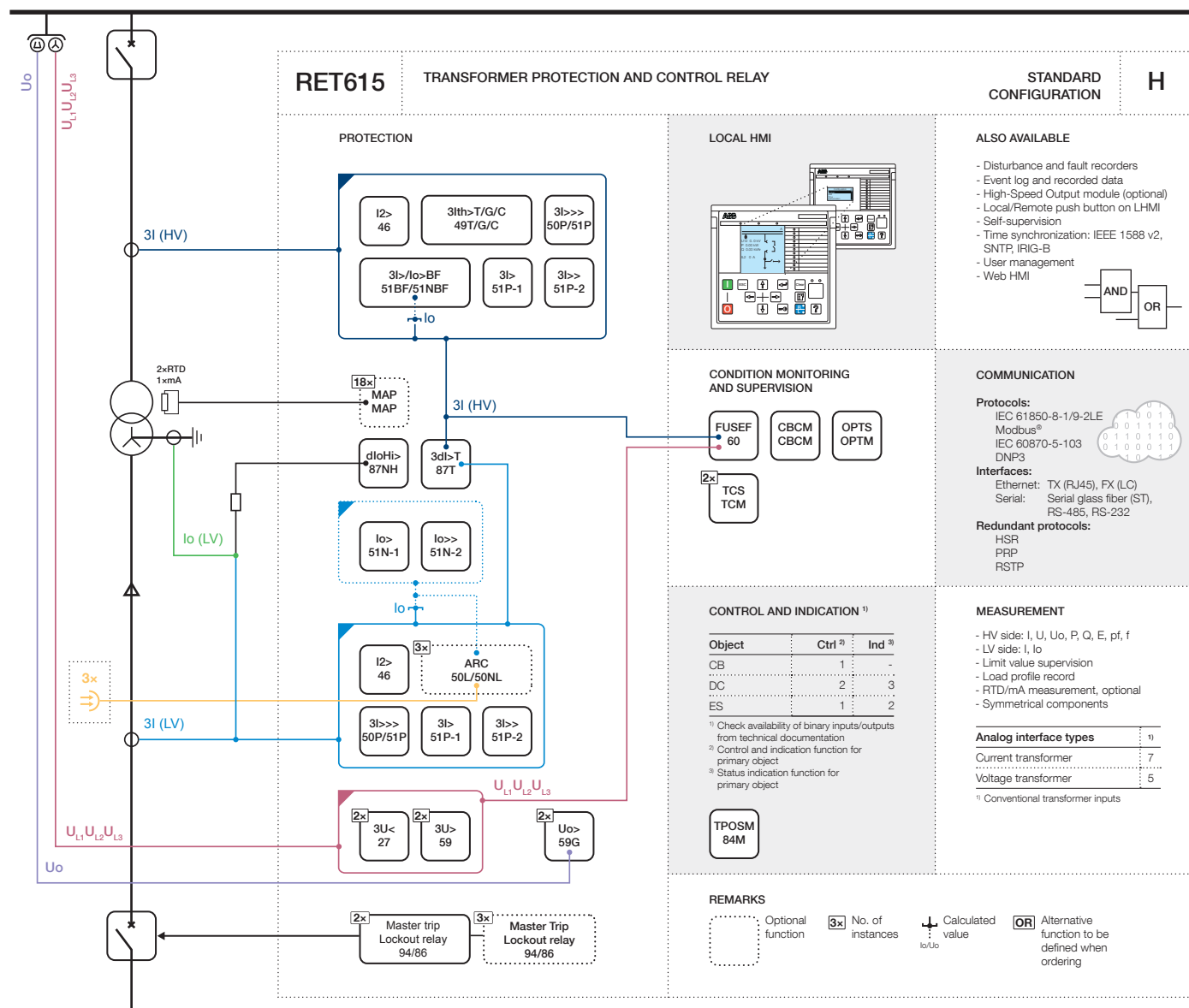


Figure 8. Functionality overview for standard configuration H

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Table 1. Standard configurations

Description	Std. conf.
Transformer differential with low-impedance restricted earth-fault protection on the HV side	A
Transformer differential with low-impedance restricted earth-fault protection on the LV side	B
Transformer differential with high-impedance restricted earth-fault protection on the HV side	C
Transformer differential with high-impedance restricted earth-fault protection on the LV side	D
Transformer differential with voltage protection and measurements, and low-impedance restricted earth-fault protection on the HV side	E
Transformer differential with voltage protection and measurements, and low-impedance restricted earth-fault protection on the LV side	F
Transformer differential with voltage protection and measurements, and high-impedance restricted earth-fault protection on the HV side	G
Transformer differential with voltage protection and measurements, and high-impedance restricted earth-fault protection on the LV side	H

Table 2. Supported functions

Function	IEC 61850	A	B	C	D	E	F	G	H
Protection									
Three-phase non-directional overcurrent protection, low stage	PHLPTOC1	1 HV	1 HV	1 HV	1 HV	1 HV	1 HV	1 HV	1 HV
	PHLPTOC2	1 LV	1 LV	1 LV	1 LV	1 LV	1 LV	1 LV	1 LV
Three-phase non-directional overcurrent protection, high stage	PHHPTOC1	1 HV	1 HV	1 HV	1 HV	1 HV	1 HV	1 HV	1 HV
	PHHPTOC2	1 LV	1 LV	1 LV	1 LV	1 LV	1 LV	1 LV	1 LV
Three-phase non-directional overcurrent protection, instantaneous stage	PHIPTOC1	1 HV	1 HV	1 HV	1 HV	1 HV	1 HV	1 HV	1 HV
	PHIPTOC2	1 LV	1 LV	1 LV	1 LV	1 LV	1 LV	1 LV	1 LV
Non-directional earth-fault protection, low stage	EFLPTOC1	1 HV		1 HV 1)		1 HV		1 HV 1)	
	EFLPTOC2		1 LV		1 LV 2)		1 LV		1 LV 2)
Non-directional earth-fault protection, high stage	EFHPTOC1	1 HV		1 HV 1)		1 HV		1 HV 1)	
	EFHPTOC2		1 LV		1 LV 2)		1 LV		1 LV 2)
Negative-sequence overcurrent protection	NSPTOC1	1 HV	1 HV	1 HV	1 HV	1 HV	1 HV	1 HV	1 HV
	NSPTOC2	1 LV	1 LV	1 LV	1 LV	1 LV	1 LV	1 LV	1 LV
Residual overvoltage protection	ROVPTOV					2 HV	2 HV	2 HV	2 HV
Three-phase undervoltage protection	PHPTUV					2 HV	2 HV	2 HV	2 HV
Three-phase overvoltage protection	PHPTOV					2 HV	2 HV	2 HV	2 HV
Three-phase thermal overload protection, two time constants	T2PTTR	1 HV	1 HV	1 HV	1 HV	1 HV	1 HV	1 HV	1 HV
Stabilized and instantaneous differential protection for two-winding transformers	TR2PTDF	1	1	1	1	1	1	1	1
Numerically stabilized low-impedance restricted earth-fault protection	LREFPNDF	1 HV	1 LV			1 HV	1 LV		
High-impedance based restricted earth-fault protection	HREFPDIF			1 HV	1 LV 3)			1 HV	1 LV 3)
Circuit breaker failure protection	CCBRBRF	1 HV 1)	1 HV 1)	1 HV 1)	1 HV 1)	1 HV 1)	1 HV 1)	1 HV 1)	1 HV 1)
Master trip	TRPPTRC	2 (3) 4)	2 (3) 4)	2 (3) 4)	2 (3) 4)	2 (3) 4)	2 (3) 4)	2 (3) 4)	2 (3) 4)
Arc protection	ARCSARC	(3) LV 5)	(3) LV 5)	(3) LV 5)	(3) LV 5)	(3) LV 5)	(3) LV 5)	(3) LV 5)	(3) LV 5)
Multipurpose protection	MAPGAPC	18	18	18	18	18	18	18	18
Control									
Circuit-breaker control	CBXCBR	1 HV	1 HV	1 HV	1 HV	1 HV	1 HV	1 HV	1 HV
Disconnecter control	DCXSWI	2	2	2	2	2	2	2	2
Earthing switch control	ESXSWI	1	1	1	1	1	1	1	1
Disconnecter position indication	DCSXSWI	3	3	3	3	3	3	3	3
Earthing switch indication	ESSXSWI	2	2	2	2	2	2	2	2
Tap changer position indication	TPOSYLTC	1	1	1	1	1	1	1	1
Condition monitoring and supervision									
Circuit-breaker condition monitoring	SSCBR	1 HV	1 HV	1 HV	1 HV	1 HV	1 HV	1 HV	1 HV
Trip circuit supervision	TCSSCBR	2	2	2	2	2	2	2	2
Fuse failure supervision	SEQSPVC					1	1	1	1
Runtime counter for machines and devices	MDSOPT	1	1	1	1	1	1	1	1
Measurement									
Disturbance recorder	RDRE	1	1	1	1	1	1	1	1
Load profile record	LDPRLC	1	1	1	1	1	1	1	1
Fault record	FLTRFRC	1	1	1	1	1	1	1	1
Three-phase current measurement	CMMXU1	1 HV	1 HV	1 HV	1 HV	1 HV	1 HV	1 HV	1 HV
	CMMXU2	1 LV	1 LV	1 LV	1 LV	1 LV	1 LV	1 LV	1 LV
Sequence current measurement	CSMSQI1	1 HV	1 HV	1 HV	1 HV	1 HV	1 HV	1 HV	1 HV
Residual current measurement	RESCMMXU1	1 HV		1 HV		1 HV		1 HV	
	RESCMMXU2		1 LV		1 LV		1 LV		1 LV
Three-phase voltage measurement	VMMXU					1 HV	1 HV	1 HV	1 HV
Residual voltage measurement	RESVMMXU					1 HV	1 HV	1 HV	1 HV
Sequence voltage measurement	VSMSQI					1 HV	1 HV	1 HV	1 HV
Three-phase power and energy measurement	PEMMXU					1 HV	1 HV	1 HV	1 HV

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Table 2. Supported functions, continued

Function	IEC 61850	A	B	C	D	E	F	G	H
RTD/mA measurement	XRGGIO130	(1)	(1)	(1)	(1)	(1)	(1)	(1)	(1)
Frequency measurement	FMMXU					1	1	1	1
IEC 61850-9-2 LE sampled value sending ⁶⁾⁷⁾	SMVSENDER					(1)	(1)	(1)	(1)
IEC 61850-9-2 LE sampled value receiving (voltage sharing) ⁶⁾⁷⁾	SMVRCV					(1)	(1)	(1)	(1)
Other									
Minimum pulse timer (2 pcs)	TPGAPC	4	4	4	4	4	4	4	4
Minimum pulse timer (2 pcs, second resolution)	TPSGAPC	1	1	1	1	1	1	1	1
Minimum pulse timer (2 pcs, minute resolution)	TPMGAPC	1	1	1	1	1	1	1	1
Pulse timer (8 pcs)	PTGAPC	2	2	2	2	2	2	2	2
Time delay off (8 pcs)	TOFGAPC	4	4	4	4	4	4	4	4
Time delay on (8 pcs)	TONGAPC	4	4	4	4	4	4	4	4
Set-reset (8 pcs)	SRGAPC	4	4	4	4	4	4	4	4
Move (8 pcs)	MVGAPC	2	2	2	2	2	2	2	2
Generic control point (16 pcs)	SPCGAPC	2	2	2	2	2	2	2	2
Analog value scaling (4 pcs)	SCA4GAPC	4	4	4	4	4	4	4	4
Integer value move (4 pcs)	MVI4GAPC	1	1	1	1	1	1	1	1

1, 2, ... = Number of included instances. The instances of a protection function represent the number of identical protection function blocks available in the standard configuration.

() = optional

HV = The function block is to be used on the high-voltage side in the application.

LV = The function block is to be used on the low-voltage side in the application.

1) "Io calculated" is always used.

2) IoB calculated is always used.

3) "IoB measured" is always used.

4) Master trip is included and connected to the corresponding HSO in the configuration only when the BIO0007 module is used. If additionally the ARC option is selected, ARCSARC is connected in the configuration to the corresponding master trip input.

5) "IoB calculated" and "3IB" are always used.

6) Available only with IEC 61850-9-2

7) Available only with COM0031-0037

3. Protection functions

The relay features three-phase, multi-slope stabilized (biased) stage transformer differential protection and an instantaneous stage to provide fast and selective protection for phase-to-phase short circuit, winding interturn fault and bushing flash-over protection. Besides second harmonic restraint, an advanced waveform-based blocking algorithm ensures stability at transformer energization and a fifth harmonic restraint function ensures good protection stability at moderate overexcitation of power transformers. Sensitive restricted earth-fault protection completes the overall differential protection providing detection of even single phase-to-earth faults close to the neutral earthing point of the transformer. Either the conventional high-impedance scheme or a numerical low-impedance scheme can be selected for protection of the transformer windings. When low-impedance restricted earth-fault protection is used neither stabilizing resistors nor varistors are needed and as a further benefit the transforming ratio of the neutral earthing CTs can differ from those of the phase current transformers. Due to its unit protection character and absolute selectivity restricted earth fault does not need to be time-graded with other protection schemes, and therefore high speed fault clearance can be achieved.

The relay also incorporates a thermal overload protection function, which supervises the thermal stress of the transformer windings to prevent premature aging of the insulation of the windings. Multiple stages of short circuit, phase overcurrent, negative-sequence and earth-fault backup protection are separately available for both sides of the power transformer. Earth-fault protection based on the measured or calculated residual voltage is also available. Depending on the chosen standard configuration the relay also features three-phase overvoltage protection, three-phase undervoltage protection and residual overvoltage protection. Further, the relay also offers circuit breaker failure protection.

Enhanced with optional hardware and software, the relay also features three light detection channels for arc fault protection of the circuit breaker, busbar and cable compartment of metal-enclosed indoor switchgear.

The arc-fault protection sensor interface is available on the optional communication module. Fast tripping increases staff safety and security and limits material damage in an arc fault situation. A binary input and output module can be selected as an option - having three high speed binary outputs (HSO) it further decreases the total operate time with typically 4...6 ms compared to the normal power outputs.

4. Application

RET615 provides main protection for two-winding power transformers and power generator-transformer blocks. The eight standard configurations offer comprehensive protection functions for detection and elimination of operational disturbance conditions and power transformer faults.

The standard configurations A, C, E and G are intended for power transformers with earthed HV side neutrals. The A and E configuration features low-impedance REF protection while the C and G configurations offer high-impedance REF protection. The B, D, F and H configurations fit transformers with solidly-earthed LV side neutral or the LV side with a neutral earthing resistor. The B, D, F and H configurations also fit applications including a separate earthing transformer located within the area of protection. The A, B, E, and F configurations also suit applications, where the turns ratio of the CT of the neutral earthing circuit differs from the turns ratio of the line CTs. The C, D, G and H configurations require that the turns ratios of the CTs are equal.

Standard configurations E, F, G and H include phase-voltage protection and measurement functions which provide two-stage power transformer overvoltage and undervoltage protection and/or supervision.

Two optional RTD/mA modules are available. The optional RTD/mA module offered for the standard configurations A-D

allows up to eight analog signals to be measured via the six RTD inputs and the two mA inputs using transducers. The RTD and mA inputs can be used for measuring the oil temperature at the bottom and top of the transformer. Furthermore, the RTD/mA inputs can be used for measuring the ambient air temperature. The RTD inputs also offer thermal protection of dry-type power transformers fitted with Pt-100 temperature sensors.

Temperature measurement over the RTD/mA inputs extends the function of the three-phase thermal overload protection of the relay. Further, one of the RTD inputs can also be used as a direct resistance measuring input for position information of the on-load tap changer. Alternatively, the tap changer position indication can be obtained via a mA-transducer.

The optional RTD/mA module offered for the standard configurations E-H allows up to three analog signals to be measured via the two RTD inputs and the one mA input using transducers. The RTD inputs can be used for measuring the oil temperature and the ambient air temperature. Temperature measurement over the RTD inputs extends the function of the three-phase thermal overload protection of the relay. For on-load tap changer, the tap changer position indication can be obtained via a mA transducer. If required, the analog temperature or tap changer position values can be sent to other devices using analog horizontal GOOSE messaging. Analog values can also be received from other devices over the station bus, thus improving the extent of relevant information.

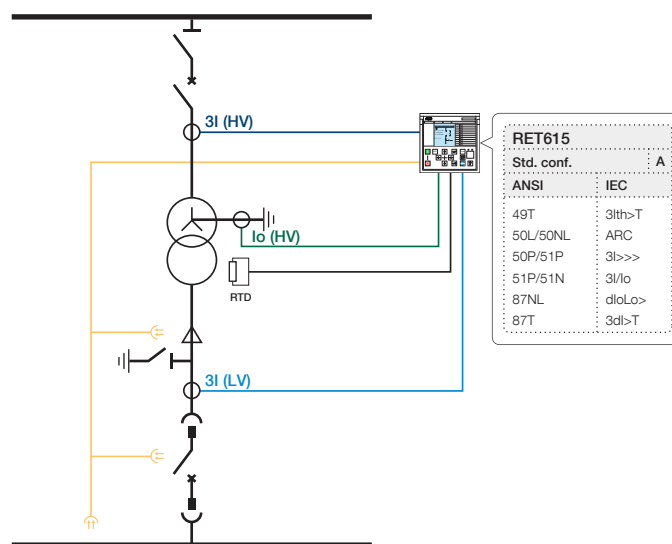


Figure 9. Protection of a two-winding power transformer with RET615 standard configuration A

Figure 9 illustrates the protection of a two-winding power transformer with RET615 standard configuration A. The main protection used in this application example is transformer

differential protection. Additionally, restricted earth-fault protection with numerical low-impedance principle is applied on the transformer's HV side.

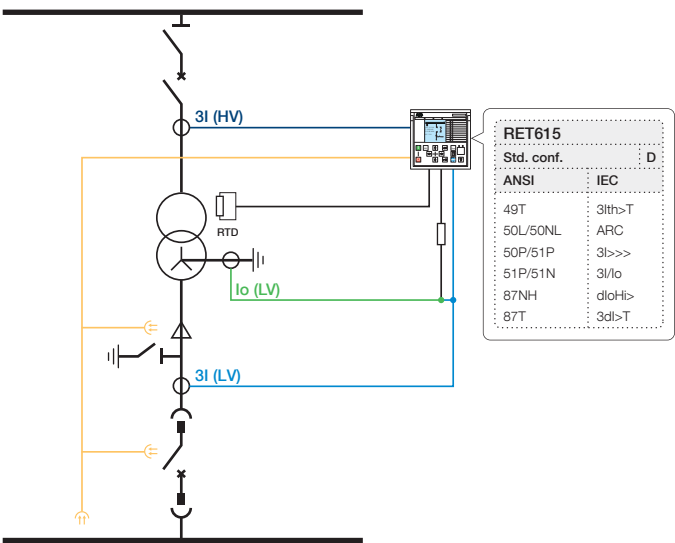


Figure 10. Protection of a two-winding power transformer with RET615 standard configuration D

Figure 10 illustrates the protection of a two-winding power transformer with RET615 standard configuration D. The main protection used in this application example is transformer

differential protection. Additionally, restricted earth-fault protection with high-impedance principle is applied on the transformer's LV side.

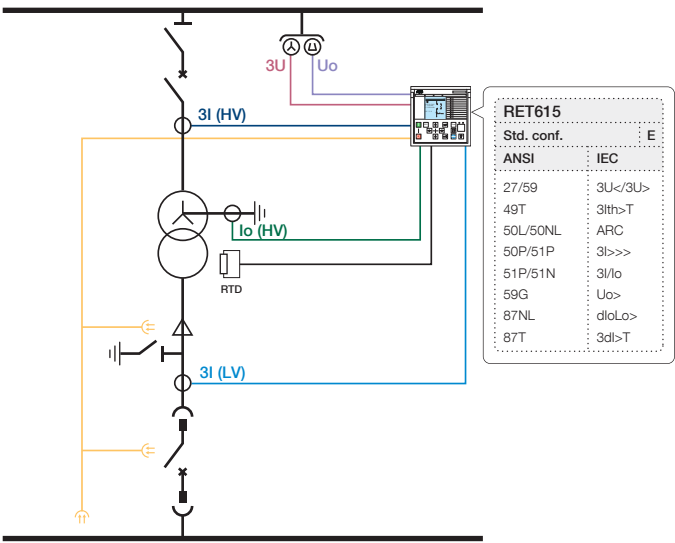
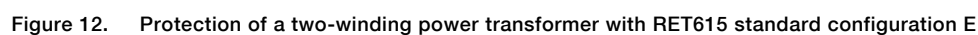


Figure 11. Protection of a two-winding power transformer with RET615 standard configuration E

Figure 11 illustrates the protection of a two-winding power transformer with RET615 standard configuration E. The main protection used in this application example is transformer

differential protection. Additionally, restricted earth-fault protection with numerical low-impedance principle and voltage based protection are applied on the transformer's HV side.



transformer's HV side. The RTD inputs of RET615 are utilized for monitoring the oil temperature and oil level of the transformer. Additionally, REU615 with the standard configuration B is used as automatic voltage regulator for the on-load tap changer of the transformer.

5. Supported ABB solutions

The 615 series protection relays together with the Substation Management Unit COM600S constitute a genuine IEC 61850 solution for reliable power distribution in utility and industrial power systems. To facilitate the system engineering, ABB's relays are supplied with connectivity packages. The connectivity packages include a compilation of software and relay-specific information, including single-line diagram templates and a full relay data model. The data model includes event and parameter lists. With the connectivity packages, the relays can be readily configured using PCM600 and integrated with COM600S or the network control and management system MicroSCADA Pro.

The 615 series relays offer native support for IEC 61850 Edition 2 also including binary and analog horizontal GOOSE messaging. In addition, process bus with the sending of sampled values of analog currents and voltages and the receiving of sampled values of voltages is supported. Compared to traditional hard-wired, inter-device signaling, peer-to-peer communication over a switched Ethernet LAN offers an advanced and versatile platform for power system protection. Among the distinctive features of the protection system approach, enabled by the full implementation of the IEC 61850 substation automation standard, are fast communication capability, continuous supervision of the protection and communication system's integrity, and an inherent flexibility regarding reconfiguration and upgrades. This protection relay series is able to optimally utilize interoperability provided by the IEC 61850 Edition 2 features.

At substation level, COM600S uses the data content of the bay-level devices to enhance substation level functionality.

COM600S features a Web browser-based HMI, which provides a customizable graphical display for visualizing single-line mimic diagrams for switchgear bay solutions. The SLD feature is especially useful when 615 series relays without the optional single-line diagram feature are used. The Web HMI of COM600S also provides an overview of the whole substation, including relay-specific single-line diagrams, which makes information easily accessible. Substation devices and processes can also be remotely accessed through the Web HMI, which improves personnel safety.

In addition, COM600S can be used as a local data warehouse for the substation's technical documentation and for the network data collected by the devices. The collected network data facilitates extensive reporting and analyzing of network fault situations by using the data historian and event handling features of COM600S. The historical data can be used for accurate monitoring of process and equipment performance, using calculations based on both real-time and historical values. A better understanding of the process dynamics is achieved by combining time-based process measurements with production and maintenance events.

COM600S can also function as a gateway and provide seamless connectivity between the substation devices and network-level control and management systems, such as MicroSCADA Pro and System 800xA.

GOOSE Analyzer interface in COM600S enables the following and analyzing the horizontal IEC 61850 application during commissioning and operation at station level. It logs all GOOSE events during substation operation to enable improved system supervision.

Table 3. Supported ABB solutions

Product	Version
Substation Management Unit COM600S	4.0 SP1 or later
	4.1 or later (Edition 2)
MicroSCADA Pro SYS 600	9.3 FP2 or later
	9.4 or later (Edition 2)
System 800xA	5.1 or later

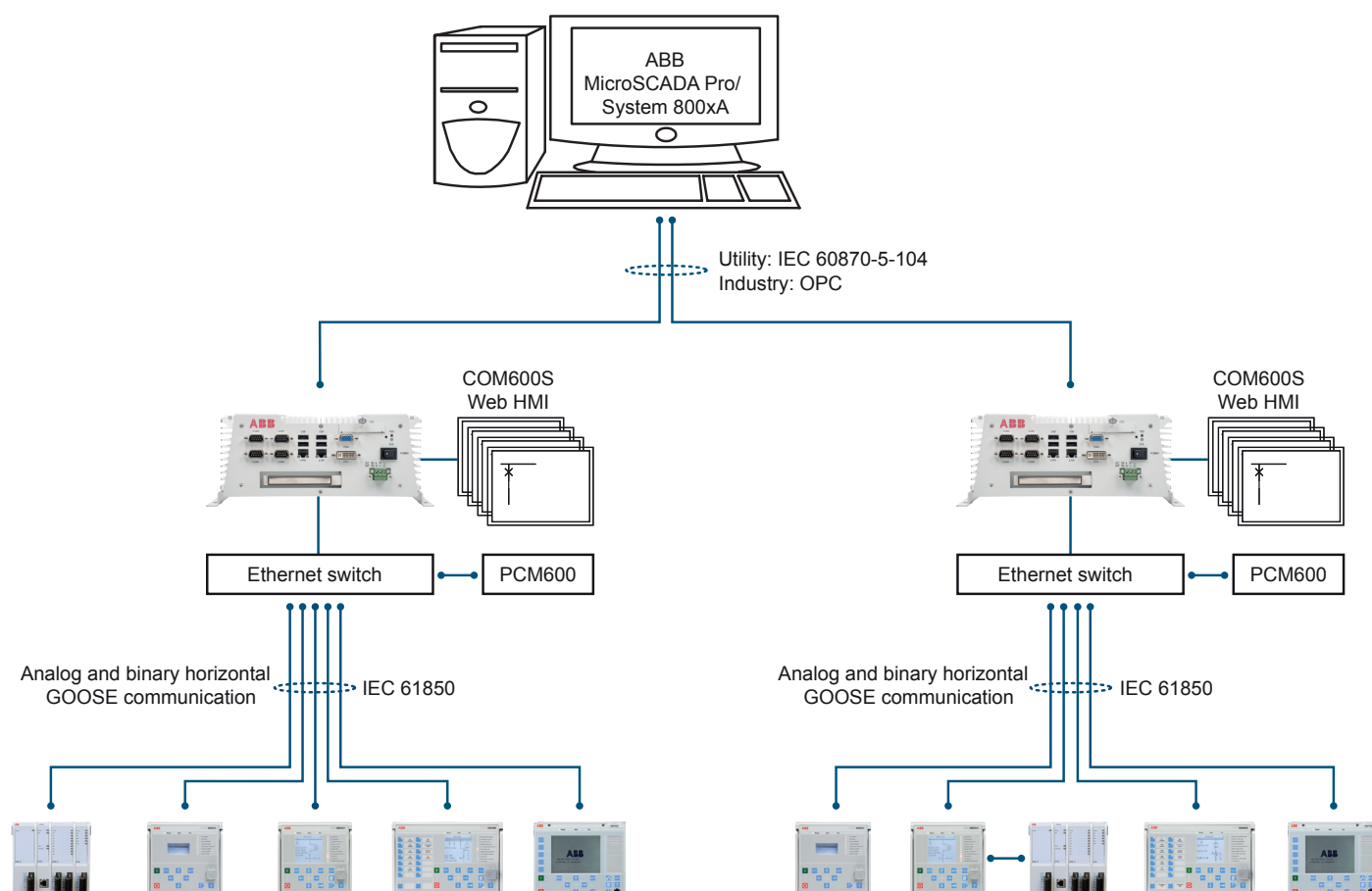


Figure 13. ABB power system example using Relion relays, COM600S and MicroSCADA Pro/System 800xA

6. Control

RET615 integrates functionality for the control of a circuit breaker via the front panel HMI or by means of remote controls. In addition to the circuit-breaker control the relay features two control blocks which are intended for motor-operated control of disconnectors or circuit breaker truck and for their position indications. Further, the relay offers one control block which is intended for motor-operated control of one earthing switch control and its position indication.

Two physical binary inputs and two physical binary outputs are needed in the relay for each controllable primary device taken into use. Depending on the chosen standard configuration of the relay the number of unused binary inputs and binary outputs varies. Further, some standard configurations also offer optional hardware modules that increase the number of available binary inputs and outputs.

If the amount of available binary inputs or outputs of the chosen standard configuration is not sufficient, the standard configuration can be modified to release some binary inputs or

outputs which have originally been configured for other purposes, when applicable, or an external input or output module, for example, RIO600 can be integrated to the relay. The binary inputs and outputs of the external I/O module can be used for the less time critical binary signals of the application. The integration enables releasing of some initially reserved binary inputs and outputs of the relay in the standard configuration.

The suitability of the binary outputs of the relay which have been selected for controlling of primary devices should be carefully verified, for example the make and carry as well as the breaking capacity. In case the requirements for the control-circuit of the primary device are not met, the use of external auxiliary relays should to be considered.

The optional large graphical LCD of the relay's HMI includes a single-line diagram (SLD) with position indication for the relevant primary devices. Interlocking schemes required by the application are configured using the signal matrix or the application configuration functionality of PCM600.

7. Measurements

The relay continuously measures the high voltage (HV) side and the low voltage (LV) side phase currents and the neutral current of the protected transformer. In addition, the relay calculates the symmetrical components of the currents and voltages, maximum current demand value over a user-selectable pre-set time frame, the active and reactive power, the power factor, and the active and reactive energy values. Calculated values are also obtained from the protection and condition monitoring functions of the relay. Depending on the standard configuration, the relay also measures the phase voltages, the residual voltage and the voltage sequence components.

For standard configuration A, B, C and D RTD/mA inputs are offered as an option. By means of the optional RTD/mA module the relay can measure up to eight analog signals such as temperature, pressure and tap changer position values via the six RTD inputs or the two mA inputs using transducers.

For standard configuration E, F, G and H RTD/mA inputs are offered as an option. By means of these inputs the relay can measure up to three analog signals such as temperature, pressure and tap changer position values via the two RTD inputs or the one mA inputs using transducers.

The measured values can be accessed via the local HMI or remotely via the communication interface of the relay. The values can also be accessed locally or remotely using the Web HMI.

The relay is provided with a load profile recorder. The load profile feature stores the historical load data captured at a periodical time interval (demand interval). The records are in COMTRADE format.

8. Disturbance recorder

The relay is provided with a disturbance recorder featuring up to 12 analog and 64 binary signal channels. The analog channels can be set to record either the waveform or the trend of the currents and voltages measured.

The analog channels can be set to trigger the recording function when the measured value falls below or exceeds the set values.

The binary signal channels can be set to start a recording either on the rising or the falling edge of the binary signal or on both.

By default, the binary channels are set to record external or internal relay signals, for example, the start or trip signals of the relay stages, or external blocking or control signals. Binary relay signals, such as protection start and trip signals, or an external relay control signal via a binary input, can be set to trigger the recording. Recorded information is stored in a non-volatile memory and can be uploaded for subsequent fault analysis.

9. Event log

To collect sequence-of-events information, the relay has a non-volatile memory capable of storing 1024 events with the associated time stamps. The non-volatile memory retains its data even if the relay temporarily loses its auxiliary supply. The event log facilitates detailed pre- and post-fault analyses of feeder faults and disturbances. The considerable capacity to process and store data and events in the relay facilitates meeting the growing information demand of future network configurations.

The sequence-of-events information can be accessed either via local HMI or remotely via the communication interface of the relay. The information can also be accessed locally or remotely using the Web HMI.

10. Recorded data

The relay has the capacity to store the records of the 128 latest fault events. The records can be used to analyze the power system events. Each record includes, for example, current, voltage and angle values and a time stamp. The fault recording can be triggered by the start or the trip signal of a protection block, or by both. The available measurement modes include DFT, RMS and peak-to-peak. Fault records store relay measurement values at the moment when any protection function starts. In addition, the maximum demand current with time stamp is separately recorded. The records are stored in the non-volatile memory.

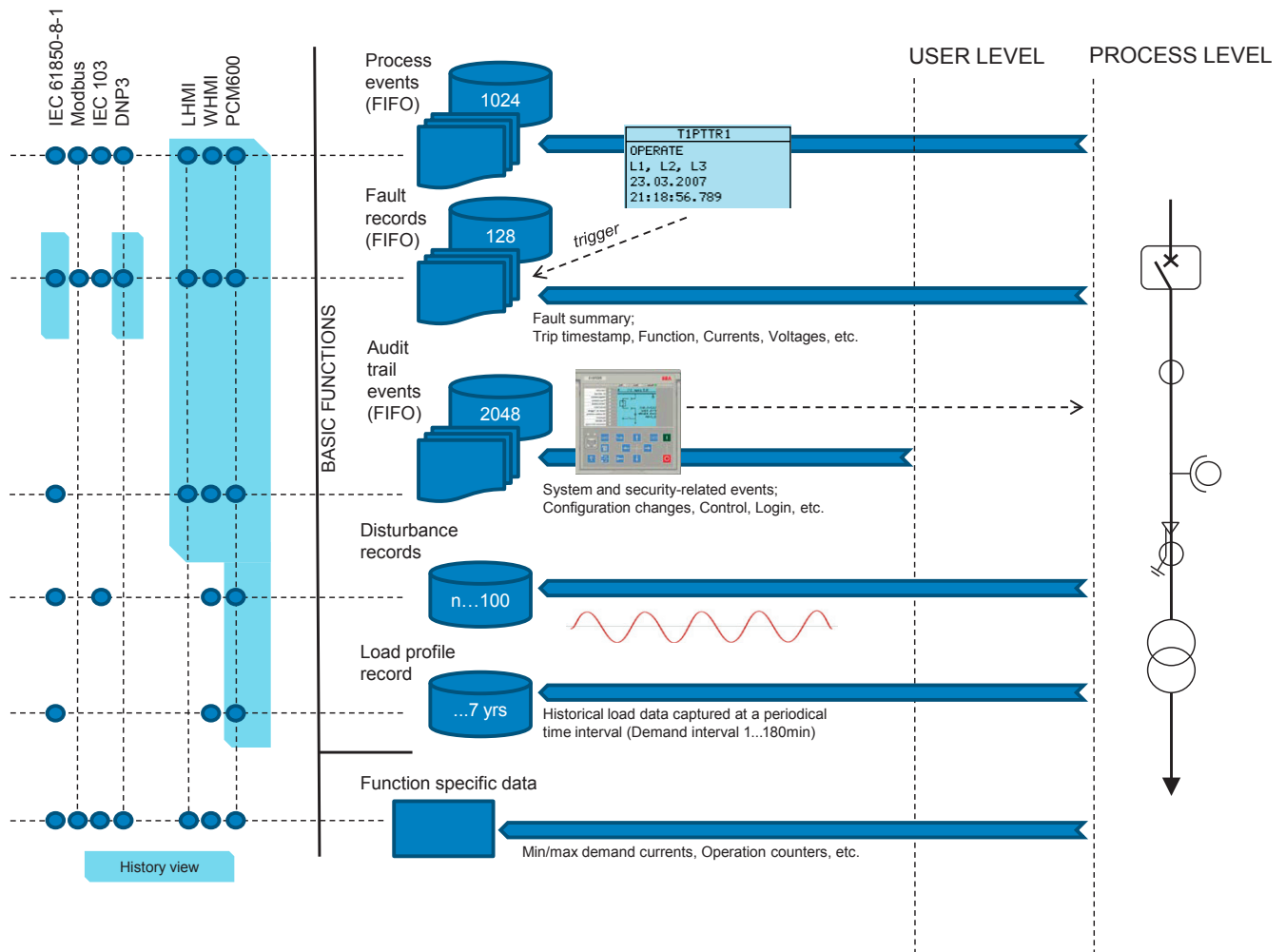


Figure 14. Recording and event capabilities overview

11. Condition monitoring

The condition monitoring functions of the relay constantly monitor the performance and the condition of the circuit breaker. The monitoring comprises the spring charging time, SF6 gas pressure, the travel time and the inactivity time of the circuit breaker.

The monitoring functions provide operational circuit breaker history data, which can be used for scheduling preventive circuit breaker maintenance.

In addition, the relay includes a runtime counter for monitoring of how many hours a protected device has been in operation thus enabling scheduling of time-based preventive maintenance of the device.

12. Trip-circuit supervision

The trip-circuit supervision continuously monitors the availability and operability of the trip circuit. It provides open-circuit monitoring both when the circuit breaker is in its closed and in its open position. It also detects loss of circuit-breaker control voltage.

13. Self-supervision

The relay's built-in self-supervision system continuously monitors the state of the relay hardware and the operation of the relay software. Any fault or malfunction detected is used for alerting the operator.

A permanent relay fault blocks the protection functions to prevent incorrect operation.

14. Fuse failure supervision

Depending on the chosen standard configuration, the relay includes fuse failure supervision functionality. The fuse failure supervision detects failures between the voltage measurement circuit and the relay. The failures are detected either by the negative sequence-based algorithm or by the delta voltage and delta current algorithm. Upon the detection of a failure, the fuse failure supervision function activates an alarm and blocks voltage-dependent protection functions from unintended operation.

15. Access control

To protect the relay from unauthorized access and to maintain information integrity, the relay is provided with a four-level, role-based authentication system with administrator-programmable individual passwords for the viewer, operator, engineer and administrator levels. The access control applies to the local HMI, the Web HMI and PCM600.

16. Inputs and outputs

The relay is equipped with six phase-current inputs and one neutral-current input or six phase-current inputs, one neutral-current input, three phase-voltage inputs and one residual voltage input. The rated level of the current inputs is 1/5 A and selectable in the relay software. The three phase-voltage inputs and the residual-voltage input covers the rated voltages 60...

210 V. Both phase-to-phase voltages and phase-to-earth voltages can be connected. In addition, the binary input thresholds 16...176 V DC are selected by adjusting the relay's parameter settings.

All binary inputs and outputs contacts are freely configurable with the signal matrix or application configuration functionality of PCM600.

As an option for standard configurations A, B, C and D, the relay offers six RTD inputs and two mA inputs. By means of the optional RTD/mA module the relay can measure up to eight analog signals such as temperature, pressure and tap changer position values via the six RTD inputs or the two mA inputs using transducers. The values can, apart from measuring and monitoring purposes, be used for tripping and alarm purposes using the offered optional multipurpose protection functions.

As an option for standard configurations E, F, G and H, the relay offers two RTD inputs and one mA input.

As an option a binary input and output module can be selected, having three high speed binary outputs (HSO), decreasing further the total operate time with typically 4...6 ms compared to the normal power outputs.

See the Input/output overview table and the terminal diagrams for more information about the inputs and outputs.

Table 4. Input/output overview

Std. conf.	Order code digit		Analog channels		Binary channels			
	5-6	7-8	CT	VT	BI	BO	RTD	mA
A B C D	BA	BB	7	-	14	4 PO + 9 SO	-	-
		FF	7	-	14	4 PO + 5 SO + 3 HSO	-	-
	BG	BA	7	-	8	4 PO + 6 SO	6	2
		FD	7	-	8	4 PO + 2 SO + 3 HSO	6	2
E F G H	BC	AD	7	5	12	4 PO + 6 SO	-	-
		FE	7	5	12	4 PO + 2 SO + 3 HSO	-	-
	BE	BA	7	5	8	4 PO + 6 SO	2	1
		FD	7	5	8	4 PO + 2 SO + 3 HSO	2	1

17. Station communication

The relay supports a range of communication protocols including IEC 61850 Edition 2, IEC 61850-9-2 LE, IEC 60870-5-103, Modbus® and DNP3. Profibus DPV1 communication protocol is supported with using the protocol converter SPA-ZC 302. Operational information and controls

are available through these protocols. However, some communication functionality, for example, horizontal communication between the relays, is only enabled by the IEC 61850 communication protocol.

The IEC 61850 protocol is a core part of the relay as the protection and control application is fully based on standard

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modelling. The relay supports Edition 2 and Edition 1 versions of the standard. With Edition 2 support, the relay has the latest functionality modelling for substation applications and the best interoperability for modern substations. It incorporates also the full support of standard device mode functionality supporting different test applications. Control applications can utilize the new safe and advanced station control authority feature.

The IEC 61850 communication implementation supports monitoring and control functions. Additionally, parameter settings, disturbance recordings and fault records can be accessed using the IEC 61850 protocol. Disturbance recordings are available to any Ethernet-based application in the standard COMTRADE file format. The relay supports simultaneous event reporting to five different clients on the station bus. The relay can exchange data with other devices using the IEC 61850 protocol.

The relay can send binary and analog signals to other devices using the IEC 61850-8-1 GOOSE (Generic Object Oriented Substation Event) profile. Binary GOOSE messaging can, for example, be employed for protection and interlocking-based protection schemes. The relay meets the GOOSE performance requirements for tripping applications in distribution substations, as defined by the IEC 61850 standard (<10 ms data exchange between the devices). The relay also supports the sending and receiving of analog values using GOOSE messaging. Analog GOOSE messaging enables easy transfer of analog measurement values over the station bus, thus facilitating for example the sending of measurement values between the relays when controlling parallel running transformers.

The relay also supports IEC 61850 process bus by sending sampled values of analog currents and voltages and by receiving sampled values of voltages. With this functionality the galvanic interpanel wiring can be replaced with Ethernet communication. The measured values are transferred as

sampled values using IEC 61850-9-2 LE protocol. The intended application for sampled values shares the voltages to other 615 series relays, having voltage based functions and 9-2 support. 615 relays with process bus based applications use IEEE 1588 for high accuracy time synchronization.

For redundant Ethernet communication, the relay offers either two optical or two galvanic Ethernet network interfaces. A third port with galvanic Ethernet network interface is also available. The third Ethernet interface provides connectivity for any other Ethernet device to an IEC 61850 station bus inside a switchgear bay, for example connection of a Remote I/O. Ethernet network redundancy can be achieved using the high-availability seamless redundancy (HSR) protocol or the parallel redundancy protocol (PRP) or a with self-healing ring using RSTP in managed switches. Ethernet redundancy can be applied to Ethernet-based IEC 61850, Modbus and DNP3 protocols.

The IEC 61850 standard specifies network redundancy which improves the system availability for the substation communication. The network redundancy is based on two complementary protocols defined in the IEC 62439-3 standard: PRP and HSR protocols. Both the protocols are able to overcome a failure of a link or switch with a zero switch-over time. In both the protocols, each network node has two identical Ethernet ports dedicated for one network connection. The protocols rely on the duplication of all transmitted information and provide a zero switch-over time if the links or switches fail, thus fulfilling all the stringent real-time requirements of substation automation.

In PRP, each network node is attached to two independent networks operated in parallel. The networks are completely separated to ensure failure independence and can have different topologies. The networks operate in parallel, thus providing zero-time recovery and continuous checking of redundancy to avoid failures.

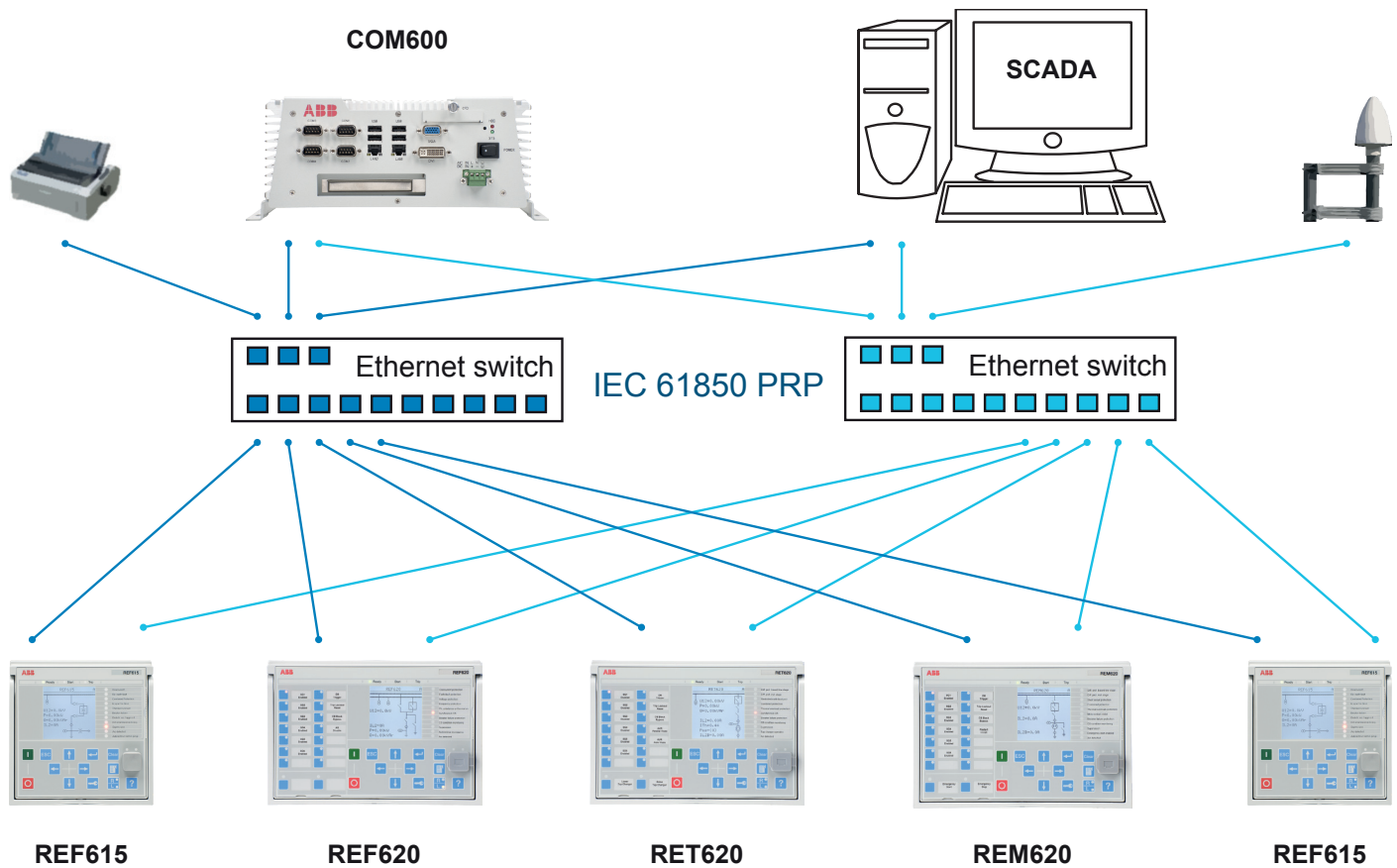


Figure 15. Parallel redundancy protocol (PRP) solution

HSR applies the PRP principle of parallel operation to a single ring. For each message sent, the node sends two frames, one through each port. Both the frames circulate in opposite directions over the ring. Every node forwards the frames it receives from one port to another to reach the next node. When the originating sender node receives the frame it sent, the

sender node discards the frame to avoid loops. The HSR ring with 615 series relays supports the connection of up to 30 relays. If more than 30 relays are to be connected, it is recommended to split the network into several rings to guarantee the performance for real-time applications.

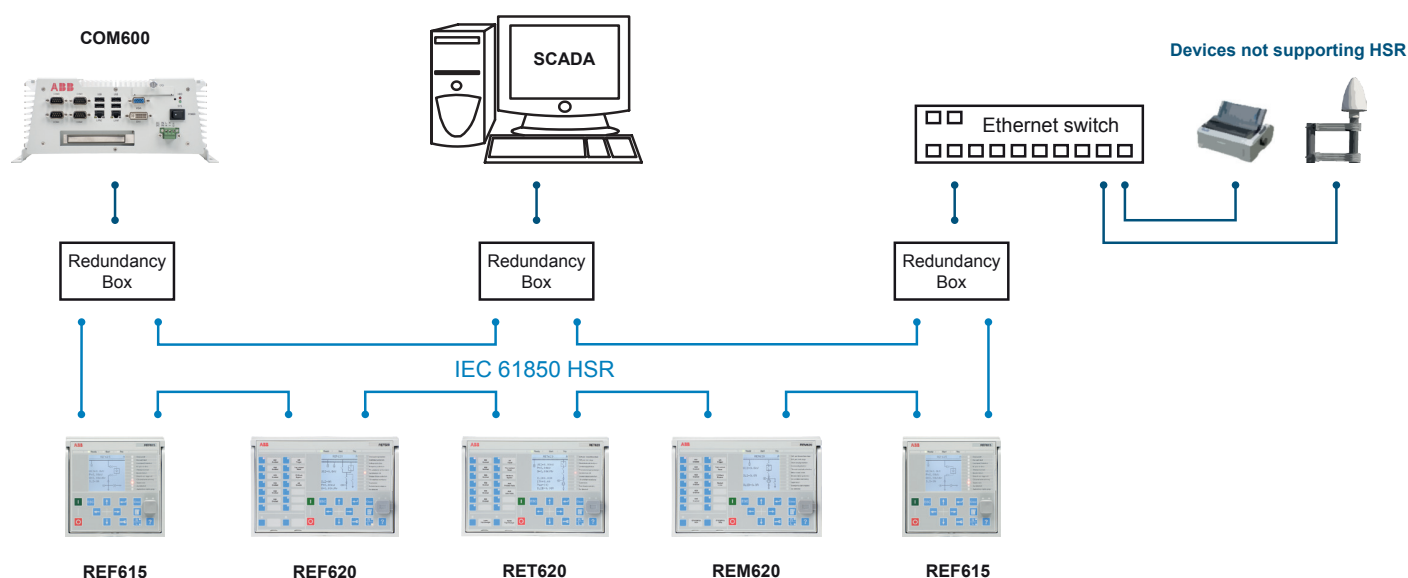


Figure 16. High availability seamless redundancy (HSR) solution

The choice between the HSR and PRP redundancy protocols depends on the required functionality, cost and complexity.

The self-healing Ethernet ring solution enables a cost-efficient communication ring controlled by a managed switch with standard Rapid Spanning Tree Protocol (RSTP) support. The managed switch controls the consistency of the loop, routes the data and corrects the data flow in case of a communication

switch-over. The relays in the ring topology act as unmanaged switches forwarding unrelated data traffic. The Ethernet ring solution supports the connection of up to 30 615 series relays. If more than 30 relays are to be connected, it is recommended to split the network into several rings. The self-healing Ethernet ring solution avoids single point of failure concerns and improves the reliability of the communication.

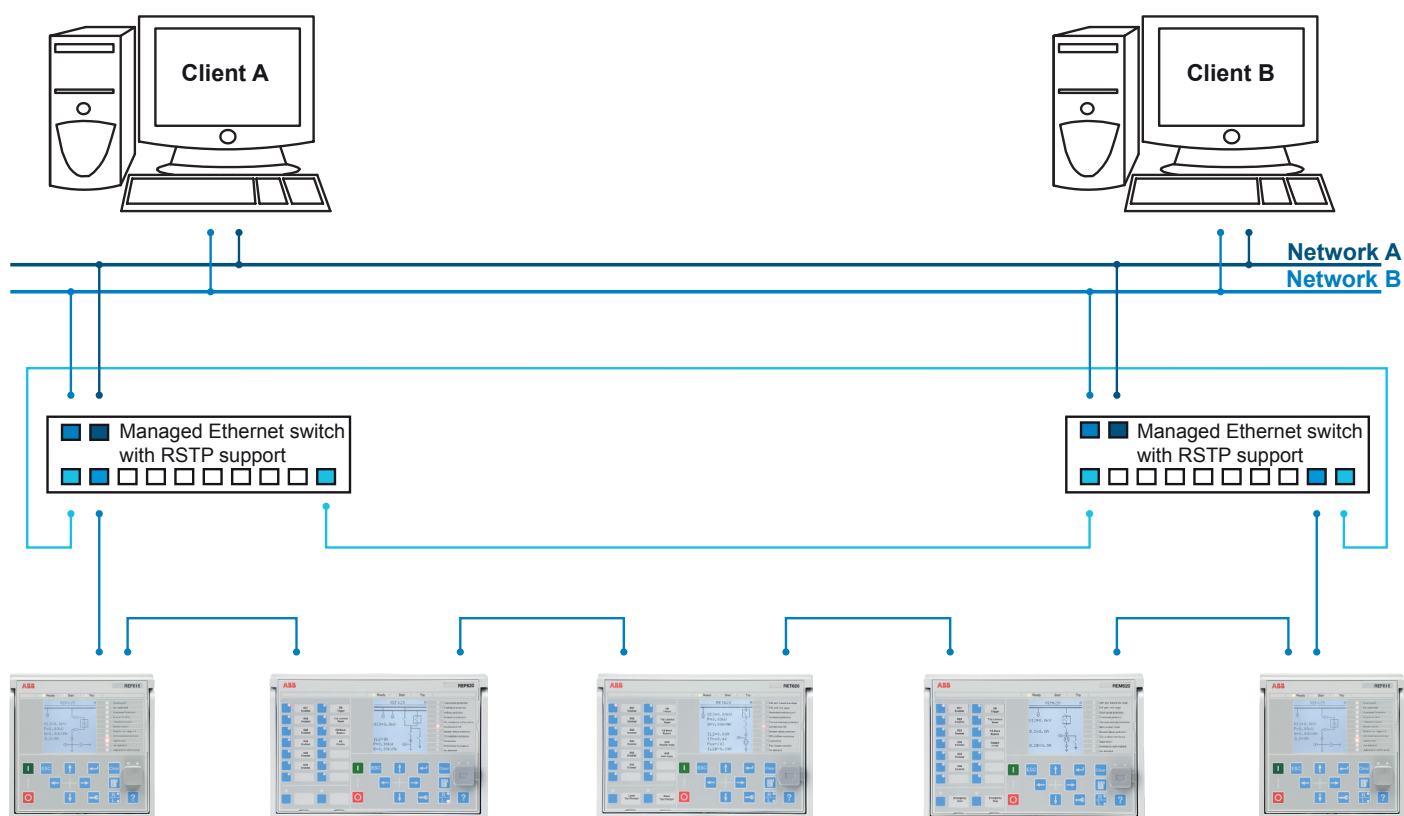


Figure 17. Self-healing Ethernet ring solution

All communication connectors, except for the front port connector, are placed on integrated optional communication modules. The relay can be connected to Ethernet-based communication systems via the RJ-45 connector (100Base-TX) or the fiber optic LC connector (100Base-FX). If connection to serial bus is required, the 9-pin RS-485 screw-terminal can be used. An optional serial interface is available for RS-232 communication.

Modbus implementation supports RTU, ASCII and TCP modes. Besides standard Modbus functionality, the relay supports retrieval of time-stamped events, changing the active setting group and uploading of the latest fault records. If a Modbus TCP connection is used, five clients can be connected to the relay simultaneously. Further, Modbus serial and Modbus TCP can be used in parallel, and if required both IEC 61850 and Modbus protocols can be run simultaneously.

The IEC 60870-5-103 implementation supports two parallel serial bus connections to two different masters. Besides basic standard functionality, the relay supports changing of the active setting group and uploading of disturbance recordings in IEC 60870-5-103 format. Further, IEC 60870-5-103 can be used at the same time with the IEC 61850 protocol.

DNP3 supports both serial and TCP modes for connection up to five masters. Changing of the active setting and reading fault

records are supported. DNP serial and DNP TCP can be used in parallel. If required, both IEC 61850 and DNP protocols can be run simultaneously.

615 series supports Profibus DPV1 with support of SPA-ZC 302 Profibus adapter. If Profibus is required the relay must be ordered with Modbus serial options. Modbus implementation includes SPA-protocol emulation functionality. This functionality enables connection to SPA-ZC 302.

When the relay uses the RS-485 bus for the serial communication, both two- and four wire connections are supported. Termination and pull-up/down resistors can be configured with jumpers on the communication card so external resistors are not needed.

The relay supports the following time synchronization methods with a time-stamping resolution of 1 ms.

Ethernet-based

- SNTP (Simple Network Time Protocol)

With special time synchronization wiring

- IRIG-B (Inter-Range Instrumentation Group - Time Code Format B)

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The relay supports the following high accuracy time synchronization method with a time-stamping resolution of 4 µs required especially in process bus applications.

- PTP (IEEE 1588) v2 with Power Profile

The IEEE 1588 support is included in all variants having a redundant Ethernet communication module.

IEEE 1588 v2 features

- Ordinary Clock with Best Master Clock algorithm
- One-step Transparent Clock for Ethernet ring topology
- 1588 v2 Power Profile
- Receive (slave): 1-step/2-step
- Transmit (master): 1-step

- Layer 2 mapping
- Peer to peer delay calculation
- Multicast operation

Required accuracy of grandmaster clock is +/-1 µs. The relay can work as a master clock per BMC algorithm if the external grandmaster clock is not available for short term.

The IEEE 1588 support is included in all variants having a redundant Ethernet communication module.

In addition, the relay supports time synchronization via Modbus, DNP3 and IEC 60870-5-103 serial communication protocols.

Table 5. Supported station communication interfaces and protocols

Interfaces/Protocols	Ethernet		Serial	
	100BASE-TX RJ-45	100BASE-FX LC	RS-232/RS-485	Fiber optic ST
IEC 61850-8-1	•	•	-	-
IEC 61850-9-2 LE	•	•	-	-
MODBUS RTU/ASCII	-	-	•	•
MODBUS TCP/IP	•	•	-	-
DNP3 (serial)	-	-	•	•
DNP3 TCP/IP	•	•	-	-
IEC 60870-5-103	-	-	•	•

• = Supported

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18. Technical data

Table 6. Dimensions

Description	Value	
Width	Frame	177 mm
	Case	164 mm
Height	Frame	177 mm (4U)
	Case	160 mm
Depth		201 mm (153 + 48 mm)
Weight	Complete protection relay	4.1 kg
	Plug-in unit only	2.1 kg

Table 7. Power supply

Description	Type 1	Type 2
Nominal auxiliary voltage U _n	100, 110, 120, 220, 240 V AC, 50 and 60 Hz	24, 30, 48, 60 V DC
	48, 60, 110, 125, 220, 250 V DC	
Maximum interruption time in the auxiliary DC voltage without resetting the relay	50 ms at U _n	
Auxiliary voltage variation	38...110% of U _n (38...264 V AC)	50...120% of U _n (12...72 V DC)
	80...120% of U _n (38.4...300 V DC)	
Start-up threshold		19.2 V DC (24 V DC × 80%)
Burden of auxiliary voltage supply under quiescent (P _q)/operating condition	DC <13.0 W (nominal)/<18.0 W (max.) AC <16.0 W (nominal)/<21.0 W (max.)	DC <13.0 W (nominal)/<18.0 W (max.)
Ripple in the DC auxiliary voltage	Max 15% of the DC value (at frequency of 100 Hz)	
Fuse type	T4A/250 V	

Table 8. Energizing inputs

Description		Value
Rated frequency		50/60 Hz ± 5 Hz
Current inputs	Rated current, I_n	1/5 A ¹⁾
	Thermal withstand capability:	
	• Continuously	20 A
	• For 1 s	500 A
	Dynamic current withstand:	
	• Half-wave value	1250 A
Voltage inputs	Input impedance	<20 mΩ
	Rated voltage	60...210 V AC
	Voltage withstand:	
	• Continuous	240 V AC
	• For 10 s	360 V AC
	Burden at rated voltage	<0.05 VA

1) Residual current and/or phase current

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Table 9. Binary inputs

Description	Value
Operating range	±20% of the rated voltage
Rated voltage	24...250 V DC
Current drain	1.6...1.9 mA
Power consumption	31.0...570.0 mW
Threshold voltage	16...176 V DC
Reaction time	<3 ms

Table 10. RTD/mA measurement (XRGGIO130)

Description		Value	
RTD inputs	Supported RTD sensors	100 Ω platinum 250 Ω platinum 100 Ω nickel 120 Ω nickel 250 Ω nickel 10 Ω copper	TCR 0.00385 (DIN 43760) TCR 0.00385 TCR 0.00618 (DIN 43760) TCR 0.00618 TCR 0.00618 TCR 0.00427
	Supported resistance range	0...2 kΩ	
	Maximum lead resistance (three-wire measurement)	25 Ω per lead	
	Isolation	2 kV (inputs to protective earth)	
	Response time	<4 s	
	RTD/resistance sensing current	Maximum 0.33 mA rms	
	Operation accuracy	Resistance	Temperature
		± 2.0% or ±1 Ω	±1°C 10 Ω copper: ±2°C
mA inputs	Supported current range	0...20 mA	
	Current input impedance	44 Ω ± 0.1%	
	Operation accuracy	±0.5% or ±0.01 mA	

Table 11. Signal output X100: SO1

Description	Value
Rated voltage	250 V AC/DC
Continuous contact carry	5 A
Make and carry for 3.0 s	15 A
Make and carry for 0.5 s	30 A
Breaking capacity when the control-circuit time constant L/R<40 ms	1 A/0.25 A/0.15 A
Minimum contact load	100 mA at 24 V AC/DC

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Table 12. Signal outputs and IRF output

Description	Value
Rated voltage	250 V AC/DC
Continuous contact carry	5 A
Make and carry for 3.0 s	10 A
Make and carry 0.5 s	15 A
Breaking capacity when the control-circuit time constant L/R<40 ms, at 48/110/220 V DC	1 A/0.25 A/0.15 A
Minimum contact load	10 mA at 5 V AC/DC

Table 13. Double-pole power output relays with TCS function

Description	Value
Rated voltage	250 V AC/DC
Continuous contact carry	8 A
Make and carry for 3.0 s	15 A
Make and carry for 0.5 s	30 A
Breaking capacity when the control-circuit time constant L/R<40 ms, at 48/110/220 V DC (two contacts connected in series)	5 A/3 A/1 A
Minimum contact load	100 mA at 24 V AC/DC
Trip-circuit supervision (TCS):	
• Control voltage range	20...250 V AC/DC
• Current drain through the supervision circuit	~1.5 mA
• Minimum voltage over the TCS contact	20 V AC/DC (15...20 V)

Table 14. Single-pole power output relays

Description	Value
Rated voltage	250 V AC/DC
Continuous contact carry	8 A
Make and carry for 3.0 s	15 A
Make and carry for 0.5 s	30 A
Breaking capacity when the control-circuit time constant L/R<40 ms, at 48/110/220 V DC	5 A/3 A/1 A
Minimum contact load	100 mA at 24 V AC/DC

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Table 15. High-speed output HSO with BIO0007

Description	Value
Rated voltage	250 V AC/DC
Continuous contact carry	6 A
Make and carry for 3.0 s	15 A
Make and carry for 0.5 s	30 A
Breaking capacity when the control-circuit time constant L/R <40 ms, at 48/110/220 V DC	5 A/3 A/1 A
Operate time	<1 ms
Reset	<20 ms, resistive load

Table 16. Front port Ethernet interfaces

Ethernet interface	Protocol	Cable	Data transfer rate
Front	TCP/IP protocol	Standard Ethernet CAT 5 cable with RJ-45 connector	10 Mbits/s

Table 17. Station communication link, fiber optic

Connector	Fiber type ¹⁾	Wave length	Typical max. length ²⁾	Permitted path attenuation ³⁾
LC	MM 62.5/125 or 50/125 µm glass fiber core	1300 nm	2 km	<8 dB
ST	MM 62.5/125 or 50/125 µm glass fiber core	820...900 nm	1 km	<11 dB

1) (MM) multi-mode fiber, (SM) single-mode fiber

2) Maximum length depends on the cable attenuation and quality, the amount of splices and connectors in the path.

3) Maximum allowed attenuation caused by connectors and cable together

Table 18. IRIG-B

Description	Value
IRIG time code format	B004, B005 ¹⁾
Isolation	500V 1 min
Modulation	Unmodulated
Logic level	5 V TTL
Current consumption	<4 mA
Power consumption	<20 mW

1) According to the 200-04 IRIG standard

Table 19. Lens sensor and optical fiber for arc protection

Description	Value
Fiber optic cable including lens	1.5 m, 3.0 m or 5.0 m
Normal service temperature range of the lens	-40...+100°C
Maximum service temperature range of the lens, max 1 h	+140°C
Minimum permissible bending radius of the connection fiber	100 mm

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Table 20. Degree of protection of flush-mounted protection relay

Description	Value
Front side	IP 54
Rear side, connection terminals	IP 20

Table 21. Environmental conditions

Description	Value
Operating temperature range	-25...+55°C (continuous)
Short-time service temperature range	-40...+85°C (<16h) ¹⁾²⁾
Relative humidity	<93%, non-condensing
Atmospheric pressure	86...106 kPa
Altitude	Up to 2000 m
Transport and storage temperature range	-40...+85°C

- 1) Degradation in MTBF and HMI performance outside the temperature range of -25...+55 °C
2) For relays with an LC communication interface the maximum operating temperature is +70 °C

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Table 22. Electromagnetic compatibility tests

Description	Type test value	Reference
1 MHz/100 kHz burst disturbance test		IEC 61000-4-18 IEC 60255-26, class III IEEE C37.90.1-2002
• Common mode	2.5 kV	
• Differential mode	2.5 kV	
3 MHz, 10 MHz and 30 MHz burst disturbance test		IEC 61000-4-18 IEC 60255-26, class III
• Common mode	2.5 kV	
Electrostatic discharge test		IEC 61000-4-2 IEC 60255-26 IEEE C37.90.3-2001
• Contact discharge	8 kV	
• Air discharge	15 kV	
Radio frequency interference test		
	10 V (rms) f = 150 kHz...80 MHz	IEC 61000-4-6 IEC 60255-26, class III
	10 V/m (rms) f = 80...2700 MHz	IEC 61000-4-3 IEC 60255-26, class III
	10 V/m f = 900 MHz	ENV 50204 IEC 60255-26, class III
	20 V/m (rms) f = 80...1000 MHz	IEEE C37.90.2-2004
Fast transient disturbance test		IEC 61000-4-4 IEC 60255-26 IEEE C37.90.1-2002
• All ports	4 kV	
Surge immunity test		IEC 61000-4-5 IEC 60255-26
• Communication	1 kV, line-to-earth	
• Other ports	4 kV, line-to-earth 2 kV, line-to-line	
Power frequency (50 Hz) magnetic field immunity test		IEC 61000-4-8
• Continuous	300 A/m	
• 1...3 s	1000 A/m	
Pulse magnetic field immunity test	1000 A/m 6.4/16 µs	IEC 61000-4-9
Damped oscillatory magnetic field immunity test		IEC 61000-4-10
• 2 s	100 A/m	
• 1 MHz	400 transients/s	
Voltage dips and short interruptions	30%/10 ms 60%/100 ms 60%/1000 ms >95%/5000 ms	IEC 61000-4-11

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Table 22. Electromagnetic compatibility tests, continued

Description	Type test value	Reference
Power frequency immunity test	Binary inputs only	IEC 61000-4-16 IEC 60255-26, class A
• Common mode	300 V rms	
• Differential mode	150 V rms	
Conducted common mode disturbances	15 Hz...150 kHz Test level 3 (10/1/10 V rms)	IEC 61000-4-16
Emission tests		EN 55011, class A IEC 60255-26 CISPR 11 CISPR 12
• Conducted		
0.15...0.50 MHz	<79 dB (μV) quasi peak <66 dB (μV) average	
0.5...30 MHz	<73 dB (μV) quasi peak <60 dB (μV) average	
• Radiated		
30...230 MHz	<40 dB (μV/m) quasi peak, measured at 10 m distance	
230...1000 MHz	<47 dB (μV/m) quasi peak, measured at 10 m distance	
1...3 GHz	<76 dB (μV/m) peak <56 dB (μV/m) average, measured at 3 m distance	
3...6 GHz	<80 dB (μV/m) peak <60 dB (μV/m) average, measured at 3 m distance	

Table 23. Insulation tests

Description	Type test value	Reference
Dielectric tests	2 kV, 50 Hz, 1 min 500 V, 50 Hz, 1 min, communication	IEC 60255-27
Impulse voltage test	5 kV, 1.2/50 μs, 0.5 J 1 kV, 1.2/50 μs, 0.5 J, communication	IEC 60255-27
Insulation resistance measurements	>100 MΩ, 500 V DC	IEC 60255-27
Protective bonding resistance	<0.1 Ω, 4 A, 60 s	IEC 60255-27

Table 24. Mechanical tests

Description	Reference	Requirement
Vibration tests (sinusoidal)	IEC 60068-2-6 (test Fc) IEC 60255-21-1	Class 2
Shock and bump test	IEC 60068-2-27 (test Ea shock) IEC 60068-2-29 (test Eb bump) IEC 60255-21-2	Class 2
Seismic test	IEC 60255-21-3	Class 2

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Table 25. Environmental tests

Description	Type test value	Reference
Dry heat test	<ul style="list-style-type: none"> 96 h at +55°C 16 h at +85°C¹⁾ 	IEC 60068-2-2
Dry cold test	<ul style="list-style-type: none"> 96 h at -25°C 16 h at -40°C 	IEC 60068-2-1
Damp heat test	<ul style="list-style-type: none"> 6 cycles (12 h + 12 h) at +25°C...+55°C, humidity >93% 	IEC 60068-2-30
Change of temperature test	<ul style="list-style-type: none"> 5 cycles (3 h + 3 h) at -25°C...+55°C 	IEC60068-2-14
Storage test	<ul style="list-style-type: none"> 96 h at -40°C 96 h at +85°C 	IEC 60068-2-1 IEC 60068-2-2

1) For relays with an LC communication interface the maximum operating temperature is +70°C

Table 26. Product safety

Description	Reference
LV directive	2006/95/EC
Standard	EN 60255-27 (2013) EN 60255-1 (2009)

Table 27. EMC compliance

Description	Reference
EMC directive	2004/108/EC
Standard	EN 60255-26 (2013)

Table 28. RoHS compliance

Description
Complies with RoHS directive 2002/95/EC

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Protection functions

Table 29. Three-phase non-directional overcurrent protection (PHxPTOC)

Characteristic	Value			
Operation accuracy	PHLPTOC	Depending on the frequency of the measured current: $f_n \pm 2$ Hz		
	PHHPTOC and PHIPTOC	$\pm 1.5\%$ of the set value or $\pm 0.002 \times I_n$ $\pm 1.5\%$ of set value or $\pm 0.002 \times I_n$ (at currents in the range of $0.1 \dots 10 \times I_n$) $\pm 5.0\%$ of the set value (at currents in the range of $10 \dots 40 \times I_n$)		
Start time ¹⁾²⁾	PHIPTOC: $I_{\text{Fault}} = 2 \times \text{set Start value}$ $I_{\text{Fault}} = 10 \times \text{set Start value}$	Minimum	Typical	Maximum
		16 ms	19 ms	23 ms
	PHHPTOC and PHLPTOC: $I_{\text{Fault}} = 2 \times \text{set Start value}$	11 ms	12 ms	14 ms
		23 ms	26 ms	29 ms
Reset time	Typically 40 ms			
Reset ratio	Typically 0.96			
Retardation time	<30 ms			
Operate time accuracy in definite time mode	$\pm 1.0\%$ of the set value or ± 20 ms			
Operate time accuracy in inverse time mode	$\pm 5.0\%$ of the theoretical value or ± 20 ms ³⁾			
Suppression of harmonics	RMS: No suppression DFT: -50 dB at $f = n \times f_n$, where $n = 2, 3, 4, 5, \dots$ Peak-to-Peak: No suppression P-to-P+backup: No suppression			

- 1) Set *Operate delay time* = 0,02 s, *Operate curve type* = IEC definite time, *Measurement mode* = default (depends on stage), current before fault = $0.0 \times I_n$, $f_n = 50$ Hz, fault current in one phase with nominal frequency injected from random phase angle, results based on statistical distribution of 1000 measurements
- 2) Includes the delay of the signal output contact
- 3) Includes the delay of the heavy-duty output contact

Table 30. Three-phase non-directional overcurrent protection (PHxPTOC) main settings

Parameter	Function	Value (Range)	Step
Start value	PHLPTOC	$0.05 \dots 5.00 \times I_n$	0.01
	PHHPTOC	$0.10 \dots 40.00 \times I_n$	0.01
	PHIPTOC	$1.00 \dots 40.00 \times I_n$	0.01
Time multiplier	PHLPTOC and PHHPTOC	0.05...15.00	0.01
Operate delay time	PHLPTOC and PHHPTOC	40...200000 ms	10
	PHIPTOC	20...200000 ms	10
Operating curve type ¹⁾	PHLPTOC	Definite or inverse time Curve type: 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, 17, 18, 19	
	PHHPTOC	Definite or inverse time Curve type: 1, 3, 5, 9, 10, 12, 15, 17	
	PHIPTOC	Definite time	

- 1) For further reference, see the Operation characteristics table

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Table 31. Non-directional earth-fault protection (EFxPTOC)

Characteristic	Value			
Operation accuracy		Depending on the frequency of the measured current: $f_n \pm 2$ Hz		
	EFLPTOC	$\pm 1.5\%$ of the set value or $\pm 0.002 \times I_n$		
	EFHPTOC and EFIPTOC	$\pm 1.5\%$ of set value or $\pm 0.002 \times I_n$ (at currents in the range of $0.1 \dots 10 \times I_n$) $\pm 5.0\%$ of the set value (at currents in the range of $10 \dots 40 \times I_n$)		
Start time ¹⁾²⁾		Minimum	Typical	Maximum
	EFIPTOC:			
	$I_{Fault} = 2 \times \text{set Start value}$	16 ms	19 ms	23 ms
	$I_{Fault} = 10 \times \text{set Start value}$	11 ms	12 ms	14 ms
	EFHPTOC and EFLPTOC:			
	$I_{Fault} = 2 \times \text{set Start value}$	23 ms	26 ms	29 ms
Reset time	Typically 40 ms			
Reset ratio	Typically 0.96			
Retardation time	<30 ms			
Operate time accuracy in definite time mode	$\pm 1.0\%$ of the set value or ± 20 ms			
Operate time accuracy in inverse time mode	$\pm 5.0\%$ of the theoretical value or ± 20 ms ³⁾			
Suppression of harmonics	RMS: No suppression DFT: -50 dB at $f = n \times f_n$, where $n = 2, 3, 4, 5, \dots$ Peak-to-Peak: No suppression			

1) *Measurement mode* = default (depends on stage), current before fault = $0.0 \times I_n$, $f_n = 50$ Hz, earth-fault current with nominal frequency injected from random phase angle, results based on statistical distribution of 1000 measurements

2) Includes the delay of the signal output contact

3) Maximum *Start value* = $2.5 \times I_n$, *Start value* multiples in range of 1.5...20

Table 32. Non-directional earth-fault protection (EFxPTOC) main settings

Parameter	Function	Value (Range)	Step
Start value	EFLPTOC	$0.010 \dots 5.000 \times I_n$	0.005
	EFHPTOC	$0.10 \dots 40.00 \times I_n$	0.01
	EFIPTOC	$1.00 \dots 40.00 \times I_n$	0.01
Time multiplier	EFLPTOC and EFHPTOC	0.05...15.00	0.01
Operate delay time	EFLPTOC and EFHPTOC	40...200000 ms	10
	EFIPTOC	20...200000 ms	10
Operating curve type ¹⁾	EFLPTOC	Definite or inverse time Curve type: 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, 17, 18, 19	
	EFHPTOC	Definite or inverse time Curve type: 1, 3, 5, 9, 10, 12, 15, 17	
	EFIPTOC	Definite time	

1) For further reference, see the Operation characteristics table

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Table 33. Negative-sequence overcurrent protection (NSPTOC)

Characteristic		Value		
Operation accuracy		Depending on the frequency of the measured current: f_n		
		$\pm 1.5\%$ of the set value or $\pm 0.002 \times I_n$		
Start time ¹⁾²⁾		Minimum	Typical	Maximum
	$I_{Fault} = 2 \times \text{set } Start \text{ value}$	23 ms	26 ms	28 ms
	$I_{Fault} = 10 \times \text{set } Start \text{ value}$	15 ms	18 ms	20 ms
Reset time		Typically 40 ms		
Reset ratio		Typically 0.96		
Retardation time		<35 ms		
Operate time accuracy in definite time mode		$\pm 1.0\%$ of the set value or ± 20 ms		
Operate time accuracy in inverse time mode		$\pm 5.0\%$ of the theoretical value or ± 20 ms ³⁾		
Suppression of harmonics		DFT: -50 dB at $f = n \times f_n$, where $n = 2, 3, 4, 5, \dots$		

1) Negative sequence current before fault = 0.0, $f_n = 50$ Hz, results based on statistical distribution of 1000 measurements

2) Includes the delay of the signal output contact

3) Maximum *Start value* = $2.5 \times I_n$, *Start value* multiples in range of 1.5...20

Table 34. Negative-sequence overcurrent protection (NSPTOC) main settings

Parameter	Function	Value (Range)	Step
Start value	NSPTOC	$0.01 \dots 5.00 \times I_n$	0.01
Time multiplier	NSPTOC	$0.05 \dots 15.00$	0.01
Operate delay time	NSPTOC	$40 \dots 200000$ ms	10
Operating curve type ¹⁾	NSPTOC	Definite or inverse time Curve type: 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, 17, 18, 19	

1) For further reference, see the Operation characteristics table

Table 35. Residual overvoltage protection (ROVPTOV)

Characteristic		Value		
Operation accuracy		Depending on the frequency of the measured voltage: $f_n \pm 2$ Hz		
		$\pm 1.5\%$ of the set value or $\pm 0.002 \times U_n$		
Start time ¹⁾²⁾	$U_{\text{Fault}} = 2 \times \text{set } \textit{Start value}$	Minimum	Typical	Maximum
		48 ms	51 ms	54 ms
Reset time		Typically 40 ms		
Reset ratio		Typically 0.96		
Retardation time		<35 ms		
Operate time accuracy in definite time mode		$\pm 1.0\%$ of the set value or ± 20 ms		
Suppression of harmonics		DFT: -50 dB at $f = n \times f_n$, where $n = 2, 3, 4, 5, \dots$		

1) Residual voltage before fault = $0.0 \times U_n$, $f_n = 50$ Hz, residual voltage with nominal frequency injected from random phase angle, results based on statistical distribution of 1000 measurements

2) Includes the delay of the signal output contact

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Table 36. Residual overvoltage protection (ROVPTOV) main settings

Parameter	Function	Value (Range)	Step
Start value	ROVPTOV	$0.010 \dots 1.000 \times U_n$	0.001
Operate delay time	ROVPTOV	40...300000 ms	1

Table 37. Three-phase undervoltage protection (PHPTUV)

Characteristic	Value			
Operation accuracy	Depending on the frequency of the voltage measured: $f_n \pm 2$ Hz $\pm 1.5\%$ of the set value or $\pm 0.002 \times U_n$			
Start time ¹⁾²⁾	$U_{Fault} = 0.9 \times \text{set Start value}$	Minimum	Typical	Maximum
		62 ms	66 ms	70 ms
Reset time	Typically 40 ms			
Reset ratio	Depends on the set <i>Relative hysteresis</i>			
Retardation time	<35 ms			
Operate time accuracy in definite time mode	$\pm 1.0\%$ of the set value or ± 20 ms			
Operate time accuracy in inverse time mode	$\pm 5.0\%$ of the theoretical value or ± 20 ms ³⁾			
Suppression of harmonics	DFT: -50 dB at $f = n \times f_n$, where $n = 2, 3, 4, 5, \dots$			

1) *Start value* = $1.0 \times U_n$, Voltage before fault = $1.1 \times U_n$, $f_n = 50$ Hz, undervoltage in one phase-to-phase with nominal frequency injected from random phase angle, results based on statistical distribution of 1000 measurements

2) Includes the delay of the signal output contact

3) Minimum *Start value* = 0.50, *Start value* multiples in range of 0.90...0.20

Table 38. Three-phase undervoltage protection (PHPTUV) main settings

Parameter	Function	Value (Range)	Step
Start value	PHPTUV	$0.05 \dots 1.20 \times U_n$	0.01
Time multiplier	PHPTUV	0.05...15.00	0.01
Operate delay time	PHPTUV	60...300000 ms	10
Operating curve type ¹⁾	PHPTUV	Definite or inverse time Curve type: 5, 15, 21, 22, 23	

1) For further reference, see the Operation characteristics table

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Table 39. Three-phase overvoltage protection (PHPTOV)

Characteristic		Value		
Operation accuracy		Depending on the frequency of the measured voltage: $f_n \pm 2$ Hz $\pm 1.5\%$ of the set value or $\pm 0.002 \times U_n$		
Start time ¹⁾²⁾	$U_{\text{Fault}} = 1.1 \times \text{set } \textit{Start value}$	Minimum	Typical	Maximum
		23 ms	27 ms	31 ms
Reset time		Typically 40 ms		
Reset ratio		Depends on the set <i>Relative hysteresis</i>		
Retardation time		<35 ms		
Operate time accuracy in definite time mode		$\pm 1.0\%$ of the set value or ± 20 ms		
Operate time accuracy in inverse time mode		$\pm 5.0\%$ of the theoretical value or ± 20 ms ³⁾		
Suppression of harmonics		DFT: -50 dB at $f = n \times f_n$, where $n = 2, 3, 4, 5, \dots$		

- 1) *Start value* = $1.0 \times U_n$, Voltage before fault = $0.9 \times U_n$, $f_n = 50$ Hz, overvoltage in one phase-to-phase with nominal frequency injected from random phase angle, results based on statistical distribution of 1000 measurements
2) Includes the delay of the signal output contact
3) Maximum *Start value* = $1.20 \times U_n$, *Start value* multiples in range of 1.10...2.00

Table 40. Three-phase overvoltage protection (PHPTOV) main settings

Parameter	Function	Value (Range)	Step
Start value	PHPTOV	$0.05 \dots 1.60 \times U_n$	0.01
Time multiplier	PHPTOV	0.05...15.00	0.01
Operate delay time	PHPTOV	40...300000 ms	10
Operating curve type ¹⁾	PHPTOV	Definite or inverse time Curve type: 5, 15, 17, 18, 19, 20	

- 1) For further reference, see the Operation characteristics table

Table 41. Three-phase thermal overload protection, two time constants (T2PTTR)

Characteristic	Value
Operation accuracy	Depending on the frequency of the measured current: $f_n \pm 2$ Hz Current measurement: $\pm 1.5\%$ of the set value or $\pm 0.002 \times I_n$ (at currents in the range of $0.01 \dots 4.00 \times I_n$)
Operate time accuracy ¹⁾	$\pm 2.0\%$ of the theoretical value or ± 0.50 s

- 1) Overload current > 1.2 x Operate level temperature

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Table 42. Three-phase thermal overload protection, two time constants (T2PTTR) main settings

Parameter	Function	Value (Range)	Step
Temperature rise	T2PTTR	0.0...200.0°C	0.1
Max temperature	T2PTTR	0.0...200.0°C	0.1
Operate temperature	T2PTTR	80.0...120.0%	0.1
Short time constant	T2PTTR	6...60000 s	1
Weighting factor p	T2PTTR	0.00...1.00	0.01
Current reference	T2PTTR	0.05...4.00 × I _n	0.01
Operation	T2PTTR	1 = on 5 = off	-

Table 43. Stabilized and instantaneous differential protection for two-winding transformers (TR2PTDF)

Characteristic	Value			
Operation accuracy	Depending on the frequency of the measured current: f _n ±2 Hz ±3.0% of the set value or ±0.002 × I _n			
Start time ¹⁾²⁾	Low stage High stage	Minimum	Typical	Maximum
		36 ms 21 ms	41 ms 22 ms	46 ms 24 ms
Reset time	Typically 40 ms			
Reset ratio	Typically 0.96			
Suppression of harmonics	DFT: -50 dB at f = n × f _n , where n = 2, 3, 4, 5, ...			

1) Current before fault = 0.0, f_n = 50 Hz, results based on statistical distribution of 1000 measurements

2) Includes the delay of the output contact. When differential current = 2 × set operate value and f_n = 50 Hz.

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Table 44. Stabilized and instantaneous differential protection for two-winding transformers (TR2PTDF) main settings

Parameter	Function	Value (Range)	Step
High operate value	TR2PTDF	500...3000 %I _r	10
Low operate value	TR2PTDF	5...50 %I _r	1
Slope section 2	TR2PTDF	10...50%	1
End section 2	TR2PTDF	100...500 %I _r	1
Restraint mode	TR2PTDF	5 = Waveform 6 = 2.h + waveform 8 = 5.h + waveform 9 = 2.h + 5.h + wav	-
Start value 2.H	TR2PTDF	7...20%	1
Start value 5.H	TR2PTDF	10...50%	1
Operation	TR2PTDF	1 = on 5 = off	-
Winding 1 type	TR2PTDF	1 = Y 2 = YN 3 = D 4 = Z 5 = ZN	-
Winding 2 type	TR2PTDF	1 = y 2 = yn 3 = d 4 = z 5 = zn	-
Zro A elimination	TR2PTDF	1 = Not eliminated 2 = Winding 1 3 = Winding 2 4 = Winding 1 and 2	-

Table 45. Numerically stabilized low-impedance restricted earth-fault protection (LREFPNDF)

Characteristic		Value		
Operation accuracy		Depending on the frequency of the measured current: $f_n \pm 2$ Hz		
		$\pm 2.5\%$ of the set value or $\pm 0.002 \times I_n$		
Start time ¹⁾²⁾	$I_{Fault} = 2.0 \times \text{set } Operate \text{ value}$	Minimum	Typical	Maximum
		37 ms	41 ms	45 ms
Reset time		Typically 40 ms		
Reset ratio		Typically 0.96		
Retardation time		<35 ms		
Operate time accuracy in definite time mode		$\pm 1.0\%$ of the set value or ± 20 ms		
Suppression of harmonics		DFT: -50 dB at $f = n \times f_n$, where $n = 2, 3, 4, 5, \dots$		

1) Current before fault = 0.0, $f_n = 50$ Hz, results based on statistical distribution of 1000 measurements

2) Includes the delay of the signal output contact

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Table 46. Stabilized restricted earth-fault protection (LREFPNDF) main settings

Parameter	Function	Value (Range)	Step
Operate value	LREFPNDF	5...50 %I _n	1
Minimum operate time	LREFPNDF	40...300000 ms	1
Restraint mode	LREFPNDF	1 = None 2 = Harmonic2	-
Start value 2.H	LREFPNDF	10...50%	1
Operation	LREFPNDF	1 = on 5 = off	-

Table 47. High-impedance based restricted earth-fault protection (HREFPDIF)

Characteristic	Value
Operation accuracy	At the frequency $f = f_n$ $\pm 1.5\%$ of the set value or $\pm 0.002 \times I_n$
Start time ¹⁾²⁾	$I_{\text{Fault}} = 2.0 \times \text{set Operate value}$ Typically 22 ms (± 5 ms) $I_{\text{Fault}} = 10.0 \times \text{set Operate value}$ Typically 15 ms (± 5 ms)
Reset time	<60 ms
Reset ratio	Typically 0.96
Retardation time	<60 ms
Operate time accuracy in definite time mode	$\pm 1.0\%$ of the set value or ± 20 ms

1) Current before fault = $0.0 \times I_n$, $f_n = 50$ Hz

2) Includes the delay of the signal output contact

Table 48. High-impedance based restricted earth-fault protection (HREFPDIF) main settings

Parameter	Function	Value (Range)	Step
Operate value	HREFPDIF	1.0...50.0%I _n	0.1
Minimum operate time	HREFPDIF	40...300000 ms	1
Operation	HREFPDIF	1 = on 5 = off	-

Table 49. Circuit breaker failure protection (CCBRBRF)

Characteristic	Value
Operation accuracy	Depending on the frequency of the measured current: $f_n \pm 2$ Hz $\pm 1.5\%$ of the set value or $\pm 0.002 \times I_n$
Operate time accuracy	$\pm 1.0\%$ of the set value or ± 20 ms
Reset time	Typically 40 ms
Retardation time	<20 ms

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Table 50. Circuit breaker failure protection (CCBRBRF) main settings

Parameter	Function	Value (Range)	Step
Current value	CCBRBRF	0.05...2.00 × I _n	0.05
Current value Res	CCBRBRF	0.05...2.00 × I _n	0.05
CB failure mode	CCBRBRF	1 = Current 2 = Breaker status 3 = Both	-
CB fail trip mode	CCBRBRF	1 = Off 2 = Without check 3 = Current check	-
Retrip time	CCBRBRF	0...60000 ms	10
CB failure delay	CCBRBRF	0...60000 ms	10
CB fault delay	CCBRBRF	0...60000 ms	10

Table 51. Arc protection (ARCSARC)

Characteristic		Value		
Operation accuracy		±3% of the set value or $\pm 0.01 \times I_n$		
Operate time		Minimum	Typical	Maximum
	<i>Operation mode</i> = "Light +current" ¹⁾²⁾	9 ms ³⁾	12 ms ³⁾	15 ms ³⁾
		4 ms ⁴⁾	6 ms ⁴⁾	9 ms ⁴⁾
	<i>Operation mode</i> = "Light only" ²⁾	9 ms ³⁾	10 ms ³⁾	12 ms ³⁾
4 ms ⁴⁾		6 ms ⁴⁾	7 ms ⁴⁾	
Reset time		Typically 40 ms		
Reset ratio		Typically 0.96		

- 1) *Phase start value* = 1.0 × I_n, current before fault = 2.0 × set *Phase start value*, f_n = 50 Hz, fault with nominal frequency, results based on statistical distribution of 200 measurements
- 2) Includes the delay of the heavy-duty output contact
- 3) Normal power output
- 4) High-speed output

Table 52. Arc protection (ARCSARC) main settings

Parameter	Function	Value (Range)	Step
Phase start value	ARCSARC	0.50...40.00 × I _n	0.01
Ground start value	ARCSARC	0.05...8.00 × I _n	0.01
Operation mode	ARCSARC	1 = Light+current 2 = Light only 3 = BI controlled	-

Table 53. Multipurpose protection (MAPGAPC)

Characteristic	Value
Operation accuracy	±1.0% of the set value or ±20 ms

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Table 54. Multipurpose protection (MAPGAPC) main settings

Parameter	Function	Value (Range)	Step
Start value	MAPGAPC	-10000.0...10000.0	0.1
Operate delay time	MAPGAPC	0...200000 ms	100
Operation mode	MAPGAPC	1 = Over 2 = Under	-

Table 55. Operation characteristics

Parameter	Value (Range)
Operating curve type	1 = ANSI Ext. inv. 2 = ANSI Very. inv. 3 = ANSI Norm. inv. 4 = ANSI Mod inv. 5 = ANSI Def. Time 6 = L.T.E. inv. 7 = L.T.V. inv. 8 = L.T. inv. 9 = IEC Norm. inv. 10 = IEC Very inv. 11 = IEC inv. 12 = IEC Ext. inv. 13 = IEC S.T. inv. 14 = IEC L.T. inv 15 = IEC Def. Time 17 = Programmable 18 = RI type 19 = RD type
Operating curve type (voltage protection)	5 = ANSI Def. Time 15 = IEC Def. Time 17 = Inv. Curve A 18 = Inv. Curve B 19 = Inv. Curve C 20 = Programmable 21 = Inv. Curve A 22 = Inv. Curve B 23 = Programmable

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Control functions

Table 56. Tap changer position indication (TPOSYLTC)

Description	Value
Response time for binary inputs	Typical 100 ms

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Condition and supervision functions

Table 57. Circuit-breaker condition monitoring (SSCBR)

Characteristic	Value
Current measuring accuracy	$\pm 1.5\%$ or $\pm 0.002 \times I_n$ (at currents in the range of $0.1 \dots 10 \times I_n$) $\pm 5.0\%$ (at currents in the range of $10 \dots 40 \times I_n$)
Operate time accuracy	$\pm 1.0\%$ of the set value or ± 20 ms
Travelling time measurement	+10 ms / -0 ms

Table 58. Fuse failure supervision (SEQSPVC)

Characteristic		Value	
Operate time ¹⁾	NPS function	$U_{\text{Fault Lev}} = 1.1 \times \text{set Neg Seq voltage}$	<33 ms
		$U_{\text{Fault Lev}} = 5.0 \times \text{set Neg Seq voltage}$	<18 ms
	Delta function	$\Delta U = 1.1 \times \text{set Voltage change rate}$	<30 ms
		$\Delta U = 2.0 \times \text{set Voltage change rate}$	<24 ms

1) Includes the delay of the signal output contact, $f_n = 50$ Hz, fault voltage with nominal frequency injected from random phase angle, results based on statistical distribution of 1000 measurements

Table 59. Runtime counter for machines and devices (MDSOPT)

Description	Value
Motor runtime measurement accuracy ¹⁾	$\pm 0.5\%$

1) Of the reading, for a stand-alone relay, without time synchronization

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Product version: 5.0 FP1	

Measurement functions

Table 60. Three-phase current measurement (CMMXU)

Characteristic	Value
Operation accuracy	Depending on the frequency of the measured current: $f_n \pm 2$ Hz $\pm 0.5\%$ or $\pm 0.002 \times I_n$ (at currents in the range of $0.01 \dots 4.00 \times I_n$)
Suppression of harmonics	DFT: -50 dB at $f = n \times f_n$, where $n = 2, 3, 4, 5, \dots$ RMS: No suppression

Table 61. Sequence current measurement (CSMSQI)

Characteristic	Value
Operation accuracy	Depending on the frequency of the measured current: $f/f_n = \pm 2$ Hz $\pm 1.0\%$ or $\pm 0.002 \times I_n$ at currents in the range of $0.01 \dots 4.00 \times I_n$
Suppression of harmonics	DFT: -50 dB at $f = n \times f_n$, where $n = 2, 3, 4, 5, \dots$

Table 62. Residual current measurement (RESCMMXU)

Characteristic	Value
Operation accuracy	Depending on the frequency of the current measured: $f/f_n = \pm 2$ Hz $\pm 0.5\%$ or $\pm 0.002 \times I_n$ at currents in the range of $0.01 \dots 4.00 \times I_n$
Suppression of harmonics	DFT: -50 dB at $f = n \times f_n$, where $n = 2, 3, 4, 5, \dots$ RMS: No suppression

Table 63. Three-phase voltage measurement (VMMXU)

Characteristic	Value
Operation accuracy	Depending on the frequency of the voltage measured: $f_n \pm 2$ Hz At voltages in range $0.01 \dots 1.15 \times U_n$ $\pm 0.5\%$ or $\pm 0.002 \times U_n$
Suppression of harmonics	DFT: -50 dB at $f = n \times f_n$, where $n = 2, 3, 4, 5, \dots$ RMS: No suppression

Table 64. Residual voltage measurement (RESVMMXU)

Characteristic	Value
Operation accuracy	Depending on the frequency of the measured current: $f/f_n = \pm 2$ Hz $\pm 0.5\%$ or $\pm 0.002 \times U_n$
Suppression of harmonics	DFT: -50 dB at $f = n \times f_n$, where $n = 2, 3, 4, 5, \dots$ RMS: No suppression

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Table 65. Sequence voltage measurement (VSMSQI)

Characteristic	Value
Operation accuracy	Depending on the frequency of the voltage measured: $f_n \pm 2$ Hz At voltages in range $0.01 \dots 1.15 \times U_n$ $\pm 1.0\%$ or $\pm 0.002 \times U_n$
Suppression of harmonics	DFT: -50 dB at $f = n \times f_n$, where $n = 2, 3, 4, 5, \dots$

Table 66. Three-phase power and energy measurement (PEMMXU)

Characteristic	Value
Operation accuracy	At all three currents in range $0.10 \dots 1.20 \times I_n$ At all three voltages in range $0.50 \dots 1.15 \times U_n$ At the frequency $f_n \pm 1$ Hz $\pm 1.5\%$ for apparent power S $\pm 1.5\%$ for active power P and active energy ¹⁾ $\pm 1.5\%$ for reactive power Q and reactive energy ²⁾ ± 0.015 for power factor
Suppression of harmonics	DFT: -50 dB at $f = n \times f_n$, where $n = 2, 3, 4, 5, \dots$

1) $|PF| > 0.5$ which equals $|\cos\phi| > 0.5$

2) $|PF| < 0.86$ which equals $|\sin\phi| > 0.5$

Table 67. RTD/mA measurement (XRGGIO130)

Description	Value
RTD inputs	Supported RTD sensors
	100 Ω platinum
	250 Ω platinum
	100 Ω nickel
	120 Ω nickel
	250 Ω nickel
	10 Ω copper
	TCR 0.00385 (DIN 43760) TCR 0.00385 TCR 0.00618 (DIN 43760) TCR 0.00618 TCR 0.00618 TCR 0.00427
mA inputs	Supported resistance range
	0...2 k Ω
	Maximum lead resistance (three-wire measurement)
	25 Ω per lead
	Isolation
	2 kV (inputs to protective earth)
	Response time
	<4 s
RTD/resistance sensing current	Maximum 0.33 mA rms
	Operation accuracy
	Resistance
	$\pm 2.0\%$ or $\pm 1 \Omega$
	Temperature
	$\pm 1^\circ\text{C}$
	10 Ω copper: $\pm 2^\circ\text{C}$
mA inputs	Supported current range
	0...20 mA
	Current input impedance
mA inputs	44 $\Omega \pm 0.1\%$
	Operation accuracy
	$\pm 0.5\%$ or ± 0.01 mA

Table 68. Frequency measurement (FMMXU)

Characteristic	Value
Operation accuracy	± 5 mHz (in measurement range 35...75 Hz)

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Product version: 5.0 FP1	

Other functions

Table 69. Pulse timer (PTGAPC)

Characteristic	Value
Operate time accuracy	±1.0% of the set value or ±20 ms

Table 70. Time delay off (8 pcs) (TOFPAGC)

Characteristic	Value
Operate time accuracy	±1.0% of the set value or ±20 ms

Table 71. Time delay on (8 pcs) (TONGAPC)

Characteristic	Value
Operate time accuracy	±1.0% of the set value or ±20 ms

19. Local HMI

The relay is available with two optional displays, a large one and a small one. The large display is suited for relay installations where the front panel user interface is frequently used and a single line diagram is required. The small display is suited for remotely controlled substations where the relay is only occasionally accessed locally via the front panel user interface.

Both LCD displays offer front-panel user interface functionality with menu navigation and menu views. However, the large display offers increased front-panel usability with less menu scrolling and improved information overview. In addition, the large display includes a user-configurable single line diagram (SLD) with position indication for the associated primary equipment. Depending on the chosen standard configuration, the relay displays the related measuring values, apart from the

default single line diagram. The SLD view can also be accessed using the Web browser-based user interface. The default SLD can be modified according to user requirements by using the Graphical Display Editor in PCM600. The user can create up to 10 SLD pages.

The local HMI includes a push button (L/R) for local/remote operation of the relay. When the relay is in the local mode, it can be operated only by using the local front panel user interface. When the relay is in the remote mode, it can execute commands sent from a remote location. The relay supports the remote selection of local/remote mode via a binary input. This feature facilitates, for example, the use of an external switch at the substation to ensure that all relays are in the local mode during maintenance work and that the circuit breakers cannot be operated remotely from the network control center.

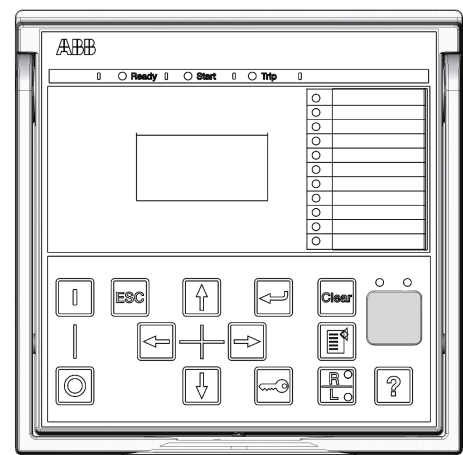


Figure 18. Small display

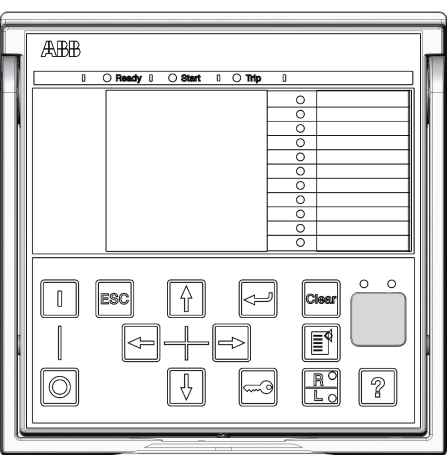


Figure 19. Large display

Table 72. Small display

Character size ¹⁾	Rows in the view	Characters per row
Small, mono-spaced (6 × 12 pixels)	5	20
Large, variable width (13 × 14 pixels)	3	8 or more

1) Depending on the selected language

Table 73. Large display

Character size ¹⁾	Rows in the view	Characters per row
Small, mono-spaced (6 × 12 pixels)	10	20
Large, variable width (13 × 14 pixels)	7	8 or more

1) Depending on the selected language

20. Mounting methods

By means of appropriate mounting accessories, the standard relay case can be flush mounted, semi-flush mounted or wall mounted. The flush mounted and wall mounted relay cases can also be mounted in a tilted position (25°) using special accessories.

Further, the relays can be mounted in any standard 19" instrument cabinet by means of 19" mounting panels available with cut-outs for one or two relays. Alternatively, the relays can be mounted in 19" instrument cabinets by means of 4U Combiflex equipment frames.

For routine testing purposes, the relay cases can be equipped with test switches, type RTXP 18, which can be mounted side by side with the relay cases.

Mounting methods

- Flush mounting
- Semi-flush mounting
- Semi-flush mounting in a 25° tilt
- Rack mounting
- Wall mounting
- Mounting to a 19" equipment frame
- Mounting with an RTXP 18 test switch to a 19" rack

Panel cut-out for flush mounting

- Height: 161.5 ± 1 mm
- Width: 165.5 ± 1 mm

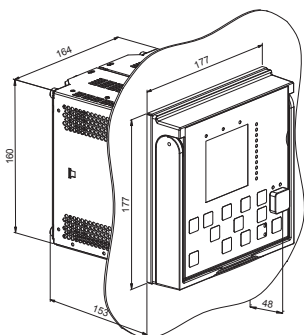


Figure 20. Flush mounting

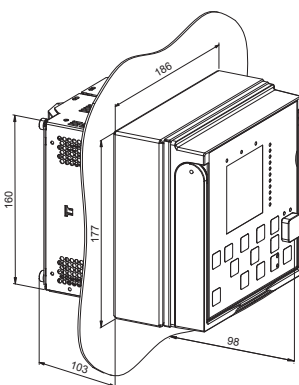


Figure 21. Semi-flush mounting

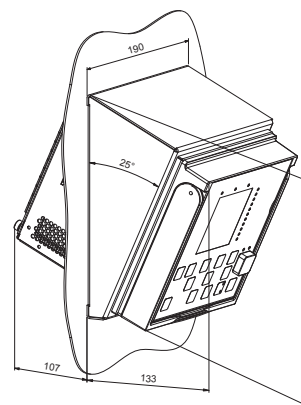


Figure 22. Semi-flush mounting in a 25° tilt

21. Relay case and plug-in unit

The relay cases are assigned to a certain type of plug-in unit. For safety reasons, the relay cases for current measuring relays are provided with automatically operating contacts for short-circuiting the CT secondary circuits when a relay unit is withdrawn from its case. The relay case is further provided with a mechanical coding system preventing the current measuring relay units from being inserted into relay cases intended for voltage measuring relay units.

22. Selection and ordering data

Use [ABB Library](#) to access the selection and ordering information and to generate the order number.

[Product Selection Tool](#) (PST), a Next-Generation Order Number Tool, supports order code creation for ABB Distribution Automation IEC products with emphasis on but not exclusively for the Relion product family. PST is an easy to use, online tool always containing the latest product information. The complete order code can be created with detailed specification and the result can be printed and mailed. Registration is required.

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23. Accessories and ordering data

Table 74. Cables

Item	Order number
Optical sensor for arc protection, cable length 1.5 m	1MRS120534-1.5
Optical sensor for arc protection, cable length 3.0 m	1MRS120534-3
Optical sensor for arc protection, cable length 5.0 m	1MRS120534-5
Optical sensor for arc protection, cable length 7.0 m	1MRS120534-7
Optical sensor for arc protection, cable length 10.0 m	1MRS120534-10
Optical sensor for arc protection, cable length 15.0 m	1MRS120534-15
Optical sensor for arc protection, cable length 20.0 m	1MRS120534-20
Optical sensor for arc protection, cable length 25.0 m	1MRS120534-25
Optical sensor for arc protection, cable length 30.0 m	1MRS120534-30

Table 75. Mounting accessories

Item	Order number
Semi-flush mounting kit	1MRS050696
Wall mounting kit	1MRS050697
Inclined semi-flush mounting kit	1MRS050831
19" rack mounting kit with cut-out for one relay	1MRS050694
19" rack mounting kit with cut-out for two relays	1MRS050695
Mounting bracket for one relay with test switch RTXP in 4U Combiflex (RHGT 19" variant C)	2RCA022642P0001
Mounting bracket for one relay in 4U Combiflex (RHGT 19" variant C)	2RCA022643P0001
19" rack mounting kit for one relay and one RTXP18 test switch (the test switch is not included in the delivery)	2RCA021952A0003
19" rack mounting kit for one relay and one RTXP24 test switch (the test switch is not included in the delivery)	2RCA022561A0003
Functional earthing flange for RTD modules ¹⁾	2RCA036978A0001
Replacement kit for a Strömberg SP_J40 series relay (cut-out in the center of the installation plate)	2RCA027871A0001
Replacement kit for a Strömberg SP_J40 series relay (cut-out on the left or the right of the installation plate)	2RCA027874A0001
Replacement kit for two Strömberg SP_J3 series relays	2RCA027880A0001
19" rack replacement kit for Strömberg SP_J3/J6 series relays (one cut-out)	2RCA027894A0001
19" rack replacement kit for Strömberg SP_J3/J6 series relays (two cut-outs)	2RCA027897A0001
Replacement kit for a Strömberg SP_J6 series relay	2RCA027881A0001
Replacement kit for three BBC S_ series relays	2RCA027882A0001
Replacement kit for a SPA 300 series relay	2RCA027885A0001

1) Cannot be used when the protection relay is mounted with the Combiflex 19" equipment frame (2RCA032826A0001)

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24. Tools

The protection relay is delivered as a preconfigured unit. The default parameter setting values can be changed from the front-panel user interface (local HMI), the Web browser-based user interface (Web HMI) or Protection and Control IED Manager PCM600 in combination with the relay-specific connectivity package.

PCM600 offers extensive relay configuration functions. For example, depending on the protection relay, the relay signals, application, graphical display and single-line diagram, and IEC 61850 communication, including horizontal GOOSE communication, can be modified with PCM600.

When the Web HMI is used, the protection relay can be accessed either locally or remotely using a Web browser

(Internet Explorer). For security reasons, the Web HMI is disabled by default but it can be enabled via the local HMI. The Web HMI functionality can be limited to read-only access.

The relay connectivity package is a collection of software and specific relay information, which enables system products and tools to connect and interact with the protection relay. The connectivity packages reduce the risk of errors in system integration, minimizing device configuration and setup times. Further, the connectivity packages for protection relays of this product series include a flexible update tool for adding one additional local HMI language to the protection relay. The update tool is activated using PCM600, and it enables multiple updates of the additional HMI language, thus offering flexible means for possible future language updates.

Table 76. Tools

Description	Version
PCM600	2.6 (Rollup 20150626) or later
Web browser	IE 8.0, IE 9.0, IE 10.0 or IE 11.0
RET615 Connectivity Package	5.1 or later

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Table 77. Supported functions

Function	Web HMI	PCM600
Relay parameter setting	•	•
Saving of relay parameter settings in the relay	•	•
Signal monitoring	•	•
Disturbance recorder handling	•	•
Alarm LED viewing	•	•
Access control management	•	•
Relay signal configuration (Signal Matrix)	-	•
Modbus® communication configuration (communication management)	-	•
DNP3 communication configuration (communication management)	-	•
IEC 60870-5-103 communication configuration (communication management)	-	•
Saving of relay parameter settings in the tool	-	•
Disturbance record analysis	-	•
XRIO parameter export/import	•	•
Graphical display configuration	-	•
Application configuration	-	•
IEC 61850 communication configuration, GOOSE (communication configuration)	-	•
Phasor diagram viewing	•	-
Event viewing	•	•
Saving of event data on the user's PC	•	•
Online monitoring	-	•

• = Supported

25. Cyber security

The relay supports role based user authentication and authorization. It can store 2048 audit trail events to a non-volatile memory. The non-volatile memory is based on a memory type which does not need battery backup or regular component exchange to maintain the memory storage. FTP

and Web HMI use TLS encryption with a minimum of 128 bit key length protecting the data in transit. In this case the used communication protocols are FTPS and HTTPS. All rear communication ports and optional protocol services can be deactivated according to the required system setup.

26. Terminal diagrams

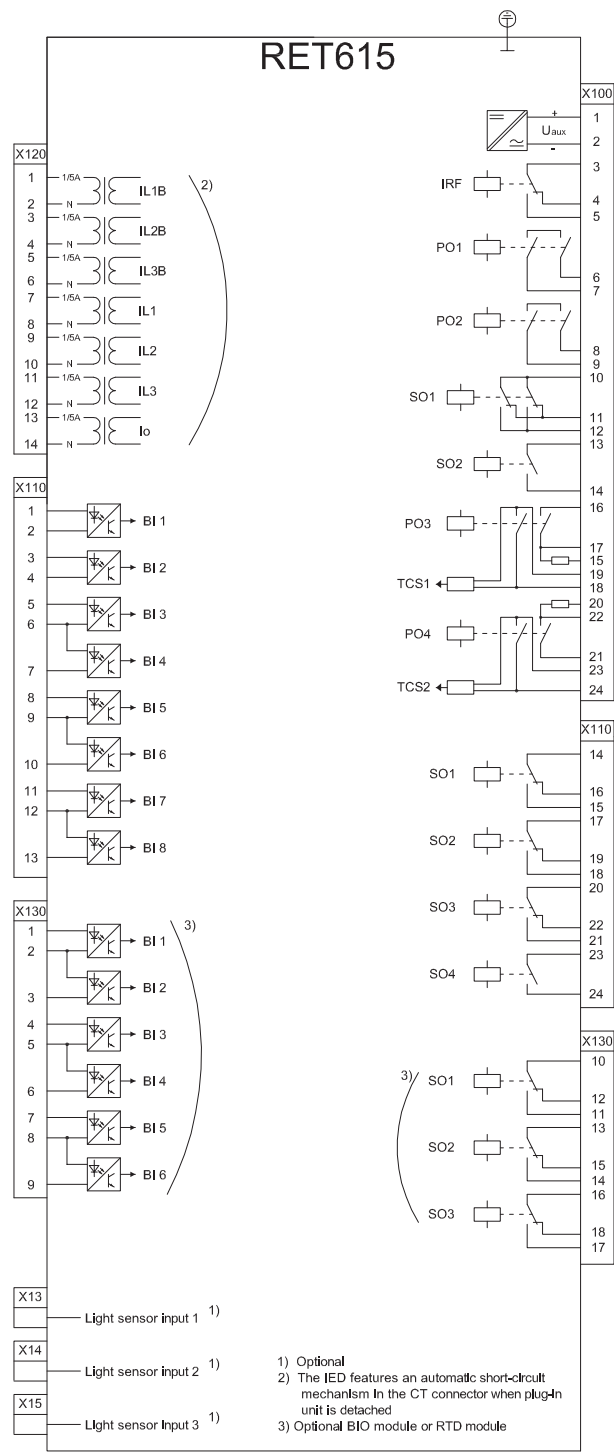


Figure 23. Terminal diagram of standard configurations A-D

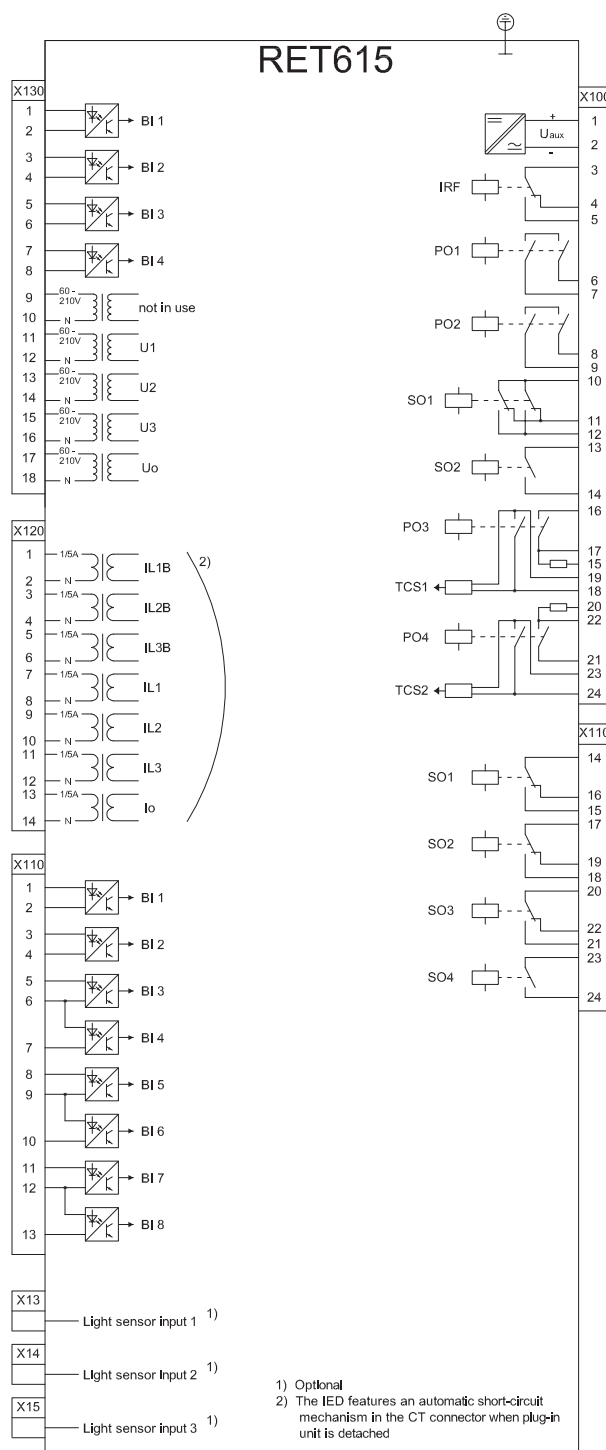


Figure 24. Terminal diagram of standard configurations E-H

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27. Certificates

DNV GL has issued an IEC 61850 Edition 2 Certificate Level A1 for Relion® 615 series. Certificate number: 74105701-OPE/INC 15-1136.

DNV GL has issued an IEC 61850 Edition 1 Certificate Level A1 for Relion® 615 series. Certificate number: 74105701-OPE/INC 15-1145.

Additional certificates can be found on the [product page](#).

28. References

The www.abb.com/substationautomation portal provides information on the entire range of distribution automation products and services.

The latest relevant information on the RET615 protection and control relay is found on the [product page](#). Scroll down the page to find and download the related documentation.

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29. Functions, codes and symbols

Table 78. Functions included in the relay

Function	IEC 61850	IEC 60617	IEC-ANSI
Protection			
Three-phase non-directional overcurrent protection, low stage	PHLPTOC1	3I> (1)	51P-1 (1)
	PHLPTOC2	3I> (2)	51P-1 (2)
Three-phase non-directional overcurrent protection, high stage	PHHPTOC1	3I>> (1)	51P-2 (1)
	PHHPTOC2	3I>> (2)	51P-2 (2)
Three-phase non-directional overcurrent protection, instantaneous stage	PHIPTOC1	3I>>> (1)	50P/51P (1)
	PHIPTOC2	3I>>> (2)	50P/51P (2)
Non-directional earth-fault protection, low stage	EFLPTOC1	Io> (1)	51N-1 (1)
	EFLPTOC2	Io> (2)	51N-1 (2)
Non-directional earth-fault protection, high stage	EFHPTOC1	Io>> (1)	51N-2 (1)
	EFHPTOC2	Io>> (2)	51N-2 (2)
Negative-sequence overcurrent protection	NSPTOC1	I2> (1)	46 (1)
	NSPTOC2	I2> (2)	46 (2)
Residual overvoltage protection	ROVPTOV1	Uo> (1)	59G (1)
	ROVPTOV2	Uo> (2)	59G (2)
Three-phase undervoltage protection	PHPTUV1	3U< (1)	27 (1)
	PHPTUV2	3U< (2)	27 (2)
Three-phase overvoltage protection	PHPTOV1	3U> (1)	59 (1)
	PHPTOV2	3U> (2)	59 (2)
Three-phase thermal overload protection, two time constants	T2PTTR1	3Ith>T/G/C (1)	49T/G/C (1)
Stabilized and instantaneous differential protection for two-winding transformers	TR2PTDF1	3dI>T (1)	87T (1)
Numerically stabilized low-impedance restricted earth-fault protection	LREFPNDF1	dIoLo> (1)	87NL (1)
High-impedance based restricted earth-fault protection	HREFPDIF1	dIoHi> (1)	87NH (1)
Circuit breaker failure protection	CCBRBRF1	3I>/Io>BF (1)	51BF/51NBF (1)
Master trip	TRPPTRC1	Master Trip (1)	94/86 (1)
	TRPPTRC2	Master Trip (2)	94/86 (2)
	TRPPTRC3	Master Trip (3)	94/86 (3)
	TRPPTRC4	Master Trip (4)	94/86 (4)
	TRPPTRC5	Master Trip (5)	94/86 (5)
Arc protection	ARCSARC1	ARC (1)	50L/50NL (1)
	ARCSARC2	ARC (2)	50L/50NL (2)
	ARCSARC3	ARC (3)	50L/50NL (3)

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Table 78. Functions included in the relay, continued

Function	IEC 61850	IEC 60617	IEC-ANSI
Multipurpose protection	MAPGAPC1	MAP (1)	MAP (1)
	MAPGAPC2	MAP (2)	MAP (2)
	MAPGAPC3	MAP (3)	MAP (3)
	MAPGAPC4	MAP (4)	MAP (4)
	MAPGAPC5	MAP (5)	MAP (5)
	MAPGAPC6	MAP (6)	MAP (6)
	MAPGAPC7	MAP (7)	MAP (7)
	MAPGAPC8	MAP (8)	MAP (8)
	MAPGAPC9	MAP (9)	MAP (9)
	MAPGAPC10	MAP (10)	MAP (10)
	MAPGAPC11	MAP (11)	MAP (11)
	MAPGAPC12	MAP (12)	MAP (12)
	MAPGAPC13	MAP (13)	MAP (13)
	MAPGAPC14	MAP (14)	MAP (14)
	MAPGAPC15	MAP (15)	MAP (15)
	MAPGAPC16	MAP (16)	MAP (16)
	MAPGAPC17	MAP (17)	MAP (17)
	MAPGAPC18	MAP (18)	MAP (18)
Control			
Circuit-breaker control	CBXCBR1	I <-> O CB (1)	I <-> O CB (1)
Disconnecter control	DCXSWI1	I <-> O DCC (1)	I <-> O DCC (1)
	DCXSWI2	I <-> O DCC (2)	I <-> O DCC (2)
Earthing switch control	ESXSWI1	I <-> O ESC (1)	I <-> O ESC (1)
Disconnecter position indication	DCSXSXI1	I <-> O DC (1)	I <-> O DC (1)
	DCSXSXI2	I <-> O DC (2)	I <-> O DC (2)
	DCSXSXI3	I <-> O DC (3)	I <-> O DC (3)
Earthing switch indication	ESSXSXI1	I <-> O ES (1)	I <-> O ES (1)
	ESSXSXI2	I <-> O ES (2)	I <-> O ES (2)
Tap changer position indication	TPOSYLTC1	TPOSM (1)	84M (1)
Condition monitoring and supervision			
Circuit-breaker condition monitoring	SSCBR1	CBCM (1)	CBCM (1)
Trip circuit supervision	TCSSCBR1	TCS (1)	TCM (1)
	TCSSCBR2	TCS (2)	TCM (2)
Fuse failure supervision	SEQSPVC1	FUSEF (1)	60 (1)
Runtime counter for machines and devices	MDSOPT1	OPTS (1)	OPTM (1)
Measurement			
Disturbance recorder	RDRE1	DR (1)	DFR (1)
Load profile record	LDPRLRC1	LOADPROF (1)	LOADPROF (1)

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Table 78. Functions included in the relay, continued

Function	IEC 61850	IEC 60617	IEC-ANSI
Fault record	FLTRFRC1	FAULTREC (1)	FAULTREC (1)
Three-phase current measurement	CMMXU1	3I (1)	3I (1)
	CMMXU2	3I (2)	3I (2)
Sequence current measurement	CSMSQI1	I1, I2, I0 (1)	I1, I2, I0 (1)
Residual current measurement	RESCMMXU1	Io (1)	In (1)
	RESCMMXU2	Io (2)	In (2)
Three-phase voltage measurement	VMMXU1	3U (1)	3V (1)
Residual voltage measurement	RESVMMXU1	Uo (1)	Vn (1)
Sequence voltage measurement	VSMSQI1	U1, U2, U0 (1)	V1, V2, V0 (1)
Three-phase power and energy measurement	PEMMXU1	P, E (1)	P, E (1)
RTD/mA measurement	XRGGIO130	X130 (RTD) (1)	X130 (RTD) (1)
Frequency measurement	FMMXU1	f (1)	f (1)
IEC 61850-9-2 LE sampled value sending	SMVSENDER	SMVSENDER	SMVSENDER
IEC 61850-9-2 LE sampled value receiving (voltage sharing)	SMVRCV	SMVRCV	SMVRCV
Other			
Minimum pulse timer (2 pcs)	TPGAPC1	TP (1)	TP (1)
	TPGAPC2	TP (2)	TP (2)
	TPGAPC3	TP (3)	TP (3)
	TPGAPC4	TP (4)	TP (4)
Minimum pulse timer (2 pcs, second resolution)	TPSGAPC1	TPS (1)	TPS (1)
Minimum pulse timer (2 pcs, minute resolution)	TPMGAPC1	TPM (1)	TPM (1)
Pulse timer (8 pcs)	PTGAPC1	PT (1)	PT (1)
	PTGAPC2	PT (2)	PT (2)
Time delay off (8 pcs)	TOFGAPC1	TOF (1)	TOF (1)
	TOFGAPC2	TOF (2)	TOF (2)
	TOFGAPC3	TOF (3)	TOF (3)
	TOFGAPC4	TOF (4)	TOF (4)
Time delay on (8 pcs)	TONGAPC1	TON (1)	TON (1)
	TONGAPC2	TON (2)	TON (2)
	TONGAPC3	TON (3)	TON (3)
	TONGAPC4	TON (4)	TON (4)
Set-reset (8 pcs)	SRGAPC1	SR (1)	SR (1)
	SRGAPC2	SR (2)	SR (2)
	SRGAPC3	SR (3)	SR (3)
	SRGAPC4	SR (4)	SR (4)
Move (8 pcs)	MVGAPC1	MV (1)	MV (1)
	MVGAPC2	MV (2)	MV (2)

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Table 78. Functions included in the relay, continued

Function	IEC 61850	IEC 60617	IEC-ANSI
Generic control point (16 pcs)	SPCGAPC1	SPC (1)	SPC (1)
	SPCGAPC2	SPC (2)	SPC (2)
Analog value scaling	SCA4GAPC1	SCA4 (1)	SCA4 (1)
	SCA4GAPC2	SCA4 (2)	SCA4 (2)
	SCA4GAPC3	SCA4 (3)	SCA4 (3)
	SCA4GAPC4	SCA4 (4)	SCA4 (4)
Integer value move	MVI4GAPC1	MVI4 (1)	MVI4 (1)

30. Document revision history

Document revision/date	Product version	History
A/2009-07-03	2.0	First release
B/2009-10-01	2.0	Content updated
C/2010-06-11	3.0	Content updated to correspond to the product version
D/2010-06-29	3.0	Terminology updated
E/2010-09-07	3.0	Content updated
F/2012-05-11	4.0	Content updated to correspond to the product version
G/2013-02-21	4.0 FP1	Content updated to correspond to the product version
H/2014-01-24	5.0	Content updated to correspond to the product version
K/2015-10-30	5.0 FP1	Content updated to correspond to the product version
L/2016-05-20	5.0 FP1	Content updated

Contact us

ABB Oy

Medium Voltage Products, Distribution Automation

P.O. Box 699

FI-65101 VAASA, Finland

Phone +358 10 22 11

Fax +358 10 22 41094

www.abb.com/mediumvoltage

www.abb.com/substationautomation

ABB India Limited,

Distribution Automation

Maneja Works

Vadodara-390013, India

Phone +91 265 6724402

Fax +91 265 6724423

www.abb.com/mediumvoltage

www.abb.com/substationautomation

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